



Product Change Notification / SYST-10QPXN700

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Product Category:

8-bit Microcontrollers

PCN Type:

Silicon Die Revision

Notification Subject:

ERRATA - PIC16(L)F18426/46 Family Silicon Errata and Data Sheet Clarification

Affected CPNs:

[SYST-10QPXN700_Affected_CPN_04112023.pdf](#)

[SYST-10QPXN700_Affected_CPN_04112023.csv](#)

Notification Text:

SYST-10QPXN700

Microchip has released a new Errata for the PIC16(L)F18426/46 Family Silicon Errata and Data Sheet Clarification of devices. If you are using one of these devices please read the document located at [PIC16\(L\)F18426/46 Family Silicon Errata and Data Sheet Clarification](#).

Notification Status: Final

Description of Change:

1) Add silicon errata for A2 and A4 which includes: 1.1.2, 1.2.1, 1.6.2, 1.7.1, 1.8.1, 1.9.1, and 1.9.2; Minor editorial updates.

Impacts to Data Sheet: None

Reason for Change: To Improve Productivity

Change Implementation Status: Complete

Estimated First Ship Date: 1 June 2023

NOTE: Please be advised that this is a change to the document only the product has not been changed.

Markings to Distinguish Revised from Unrevised Devices: Traceability Code

Attachments:

[PIC16\(L\)F18426/46 Family Silicon Errata and Data Sheet Clarification](#)

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PIC16(L)F18426/46

PIC16(L)F18426/46 Family Silicon Errata and Data Sheet Clarification

The PIC16(L)F18426/46 devices that you have received conform functionally to the current device data sheet (DS40001985C), except for the anomalies described in this document. The silicon issues discussed in the following pages are for silicon revisions with the Device and Revision IDs listed in the table below. The errata described in this document will be addressed in future revisions of the PIC16(L)F18426/46 silicon.

CAUTION

Notice: This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated in the last column of the 'Silicon Issue Summary' table apply to the current silicon revision (A4).

The silicon revision level can be identified using the current version of MPLAB® IDE and Microchip's programmers, debuggers, and emulation tools, which are available at the Microchip corporate website (www.microchip.com).

For example, to identify the silicon revision level using MPLAB IDE in conjunction with a hardware debugger:


1. Using the appropriate interface, connect the device to the hardware debugger.
2. Open an MPLAB IDE project.
3. Configure the MPLAB IDE project for the appropriate device and hardware debugger.
4. Based on the version of MPLAB IDE you are using, do one of the following:
 - a. For MPLAB IDE 8, select **Programmer > Reconnect**.
 - b. For MPLAB X IDE, select **Window > Dashboard** and click the **Refresh Debug Tool Status** icon (.
5. Depending on the development tool used, the part number and Device Revision ID value appear in the **Output** window.

Table 1. Silicon Device Identification

Part Number	Device ID	Revision ID		
		A1	A2	A4
PIC16F18426	0x30D2	0x2001	0x2002	0x2004
PIC16LF18426	0x30D3	0x2001	0x2002	0x2004
PIC16F18446	0x30D4	0x2001	0x2002	0x2004
PIC16LF18446	0x30D5	0x2001	0x2002	0x2004

Note: Refer to the **Device/Revision ID** section in the current "[PIC16\(L\)F184XX Memory Programming Specification](#)" (DS40001970) for detailed information on Device Identification and Revision IDs for your specific device.

Silicon Issue Summary

Module	Feature	Item No.	Issue Summary	Affected Revisions		
				A1	A2	A4
Analog-to-Digital Converter With Computation (ADCC)	ADCC Burst Average mode	1.1.1	ADCC Burst Average mode while in "Non-Continuous Double Sample" mode may not operate as intended	X	X	-
	Double Sample Conversion	1.1.2	An unexpected acquisition time is added between the first and second conversions	X	X	X
I ² C	Start and Stop Interrupt Functions	1.2.1	A race condition can cause the Start and/or Stop flags to be set when I ² C is enabled	X	X	X
Electrical Specifications	Minimum V _{DD} Specification	1.3.1	V _{DD} Min. specifications are changed for LF devices only	X	X	X
MSSP	SPI	1.4.1	SSPBUF may become corrupted	X	-	-
NVM	WRERR bit Operation	1.5.1	NVMERR bit is set by device Reset after being cleared by software	X	-	-
Program Flash Memory (PFM)	PFM Endurance	1.6.1	The PFM endurance is lower than specified	X	X	X
	Back to Back Writes	1.6.2	Repetitive writes may cause write/erase failures	X	X	-
Capture/Compare/PWM (CCP)	PWM mode	1.7.1	Duty cycle values are incorrect	X	X	-
Signal Measurement Timer (SMT)	Reset Bit	1.8.1	Module stops working if RST is set while prescaler setting is not zero	X	X	X
Universal Asynchronous Receiver Transmitter (UART)	Synchronous Mode Transmissions	1.9.1	Loss of second byte written in TXREG	X	X	-
	Transmit mode	1.9.2	Double byte transmit	X	X	-
Windowed Watchdog Timer	Window Operation	1.10.1	Window feature of the WWDT does not operate correctly in DOZE mode	X	-	-
Device Configuration	CONFIG2	1.11.1	Bit 2 of PWRTS[1:0] in the CONFIG2 register is not functional	X	-	-
Note: Only those issues indicated in the last column apply to the current silicon revision.						

1. Silicon Errata Issues

CAUTION

Notice: This document summarizes all silicon errata issues from all revisions of silicon, previous and current. Only the issues indicated by the bold font in the following tables apply to the current silicon revision.

1.1 Module: Analog-to-Digital Converter with Computation (ADCC)

1.1.1 ADCC Burst Average Mode

When the ADCC is operated in Burst Average mode (ADMD = 0b011 in the ADCON2 register) while enabling noncontinuous operation and double-sampling (ADCONT = 0 in the ADCON0 register and ADDSEN = 1 in the ADCON1 register), the value in the ADCNT register does not increment beyond '0b1' toward the value in the ADRPT register.

Work around

When operating the ADCC in Burst Average mode with double-sampling, enable continuous module operation (ADCONT = 1 in the ADCON0 register) and set the Stop-on-Interrupt bit (the ADSOI bit in the ADCON3 register). After the interrupt occurs, perform appropriate threshold calculations in the software and retrigger ADCC as necessary.

Alternatively, if the CPU is in Low-Power Sleep mode, the ADCC in noncontinuous Burst Average mode can be operated with a single ADC conversion (ADDSEN = 0 in the ADCON1 register). Doing so compromises noise immunity for lower power consumption by preventing the device from waking up to perform threshold calculations in the software.

Affected Silicon Revisions

A1	A2	A4
X	X	—

1.1.2 Double Sample Conversions

When enabling a Double Sample Conversion (DSEN = 1), with no Precharge time (ADPRE = 0) and no Acquisition time (ADACQ = 0), the maximum number of cycles of acquisition time is inserted prior to the second conversion. The first conversion will be performed as expected with no Precharge time and no Acquisition time. It is only between the first and second conversions where a maximum number of cycles of Acquisition time is performed unexpectedly.

Work around

Method 1:

Disable Double Sample Conversion (DSEN = 0) and perform two single conversions back to back.

Method 2:

If adding acquisition time is acceptable, then select no Precharge time, along with the desired Acquisition time.

Affected Silicon Revisions

A1	A2	A4
X	X	X

1.2 Module: Inter-Integrated Circuit (I²C)

1.2.1 The I²C Start and/or Stop Flags May Be Set When I²C Is Enabled

When I²C is enabled, erroneous Start and/or Stop conditions may be detected. This can generate erroneous I²C interrupts if enabled.

Work around

Use the following procedure to correctly detect the Start and Stop conditions:

1. Disable the Start and Stop conditions interrupt functions.
2. Enable the I²C module.
3. Wait 250 ns + six instructions cycles ($F_{OSC}/4$).
4. Clear the Start and Stop conditions interrupt flags.
5. Enable the Start and Stop conditions interrupt functions if used.

```
I2CxPIEBits.SCIE = 0;      // Disable Start condition interrupt
I2CxPIEBits.PCIE = 0;      // Disable Stop condition interrupt
I2CxCON0bits.EN = 1;       // Enable I2C
Delay();                   // Wait for 250nS + 6 instruction cycles (FOSC/4)
I2CxPIRbits.SCIF = 0;      // Clear the Start condition interrupt flags
I2CxPIRbits.PCIF = 0;      // Clear the Stop condition interrupt flags
I2CxPIEBits.SCIE = 1;      // Enable Start condition interrupt if used
I2CxPIEBits.PCIE = 1;      // Enable Stop condition interrupt if used
```

Affected Silicon Revisions

A1	A2	A4
X	X	X

1.3 Module: Electrical Specifications

1.3.1 Min V_{DD} Specification (LF Devices Only)

V_{DDMIN} specifications are changed for LF devices only at -40°C and 0°C as below.

V_{DDMIN} for -40°C to 0°C = 2.3V

V_{DDMIN} for 0°C to 25°C = 2.1V

Work around

None.

Affected Silicon Revisions

A1	A2	A4
X	X	X

1.4 Module: Host Synchronous Serial Port (MSSP)

1.4.1 MSSP SPI Client Mode

When operating in SPI Client mode, if the incoming SCK clock signal arrives during any of the conditions below, the SSPBUF Transmit Shift Register (TSR) may become corrupted. The byte transmitted to the client cannot be ensured to be correct, and the state of the WCOL bit may or may not indicate a write collision.

These conditions include:

- A write to an SFR
- A write to RAM following an SFR read
- A write to RAM before an SFR read

Work around

Method 1 (Interrupt based using \overline{SS}):

1. Connect the \overline{SS} line to both the \overline{SS} input and either an INT or IOC input pin.
2. Enable INT or IOC interrupts (interrupt on falling edge if available, otherwise, check that $\overline{SS} == 0$ when the interrupt occurs).
3. Load SSPBUF with the data to be transmitted.
4. Continue program execution.
5. When invoking the Interrupt Service Routine (ISR), do either of the following:
 - a. Add a delay that ensures the first SCK clock will be complete, or
 - b. Poll SSPSTAT.BF (while(BF == 0)), and wait for the transmission/reception to complete.

Method 2 (Bit polling based using \overline{SS}):

1. Load SSPBUF with the data to be transmitted.
2. Poll the \overline{SS} line and wait for the \overline{SS} to go active (while(!PORTx. $\overline{SS} == 0$)).
3. When \overline{SS} is active ($\overline{SS} == 0$), do either of the following:
 - a. Add a delay that ensures the first SCK clock will be complete, or
 - b. Poll SSPSTAT.BF (while(BF == 0)), and wait for the transmission/reception to complete.

Once one of these two methods is complete, it is safe to return to program execution.

Method 3 (\overline{SS} not available):

1. Load SSPBUF with the data to be transmitted.
2. Poll SSPSTAT.BF (while(BF == 0)), and wait for the transmission/reception to complete.

Affected Silicon Revisions

A1	A2	A4
X	—	—

1.5 Module: Nonvolatile Memory (NVM)

1.5.1 WRERR Bit Operation

When a Reset is issued while an NVM high voltage operation is in progress, the WRERR bit in the NVMCON1 register is set as expected. After clearing the WRERR bit, if a Reset reoccurs, the WRERR bit is set again regardless of whether an NVM operation is in progress or not. A successful write operation will clear the WRERR condition.

Work around

None.

Affected Silicon Revisions

A1	A2	A4
X	—	—

1.6 Module: Program Flash Memory (PFM)

1.6.1 Endurance of PFM is Lower than Specified

The minimum value for the Program Flash Memory (PFM) endurance specification called out as parameter number MEM30 is 1K cycles.

Work around

None.

Affected Silicon Revisions

A1	A2	A4
X	X	X

1.6.2 PFM Back to Back Writes

When repetitive writes to non-volatile memory (Program Flash Memory) are performed, it could result in write/erase failures at some locations. The issue is due to latent timing in the non-volatile memory controller which can cause the write instruction to fail under certain conditions.

Work around

To avoid the issue, the customer needs to wait an additional 100 us after the NVMCON1.WR bit has been set, allowing for the last word to be loaded into the latch. This delay is added only when the NVMCON1.LWLO bit is cleared in the software.

```
if(i == (WRITE_FLASH_BLOCKSIZE-1))
{
    // Start Flash program memory write
    NVMCON1bits.LWLO = 0;
}
NVMCON2 = 0x55;
NVMCON2 = 0xAA;
NVMCON1bits.WR = 1;
if (NVMCON1bits.LWLO==0)
{
    __delay_us(100);
}
NOP();
NOP();

writeAddr++;
}
```

Note: The `__delay_us()` function uses a `#define` macro definition. For the intrinsic `__delay_us()` function to work correctly, the value of the `_XTAL_FREQ` must be clearly defined. This macro is defined in the `device_config.h` file if the code is generated using MCC. The value of `XTAL_FREQ` is equal to the system clock frequency.

Affected Silicon Revisions

A1	A2	A4
X	X	—

1.7 Module: Pulse-Width Modulation (PWM)

1.7.1 Wrong Duty Cycle for CCP Module

While in PWM mode and the Timer2 prescaler is configured to 1:1, the duty cycle of the PWM output is as expected. When the Timer2 prescaler is changed to a value other than 1:1, while T2PR = 0 (PWM resolution of two bits), the expected duty cycle is wrong. The corrected duty cycle values are shown in the table below.

Table 1-1. Corrected Duty Cycle Values

Prescaler/CCPR	0	1	2	3	4
1:1	0%	25%	50%	75%	100%
1:2	50%	75%	50%	75%	100%
1:4...1:128	75%	75%	75%	75%	100%

Work around

None.

Affected Silicon Revisions

A1	A2	A4
X	X	—

1.8 Module: Signal Measurement Timer (SMT)

1.8.1 Reset Bit

If the SMT clock prescaler is set to any value other than '00', setting the RST bit will cause the module to stop working. The RST bit will remain at the value '1', the counter will not increment, and no interrupts will be generated. The problem is cleared by turning the module off and on, or by a device reset.

Work around

Method 1:

Do not set the RST bit; manual reset is usually not required for typical operation because the measurement logic will reset the counter automatically.

Method 2:

Write zero to the counter manually. The module enable or the clock should be disabled when using this method.

Method 3:

Use 1:1 prescaler (PS = 00).

Method 4:

Use the CLKREF subsystem to provide a prescaled clock and set PS = 00.

Affected Silicon Revisions

A1	A2	A4
X	X	X

1.9 Module: Universal Asynchronous Receiver Transmitter (UART)

1.9.1 Synchronous Mode Transmissions

In synchronous mode, if the TXREG is loaded with a new byte while the EUSART is shifting out the 8th bit of the previous byte, then only one bit of the new byte is shifted out. After this bit is shifted out, the transmission stops and the data is lost. If using 9-bit transmission, then this occurs on the 9th bit.

Work around

Write to the TXREG earlier in the transmission or wait for the TXIF flag bit to be set before writing a second byte.

Affected Silicon Revisions

A1	A2	A4
X	X	—

1.9.2 Double Byte Transmit

Under certain conditions, a byte written to the TXREG register can be transmitted twice. This happens when a byte is written to TXREG just as the TSR register becomes empty. This new byte is immediately transferred to the TSR register, but also remains in the TXREG register until the completion of the current instruction cycle. If the new byte in the TSR register is transmitted before this instruction cycle has completed, the duplicate in the TXREG register will subsequently be transferred to the TSR register on the following instruction clock cycle and transmitted.

Work around

Method 1:

Monitor the Transmit Interrupt Flag (TXIF) bit. Writes to the TXREG register can be performed once the TXIF bit is set, indicating that the TXREG register is empty. If using this method, ensure that the second byte is filled in the TXREG before bit 6 of the first byte is transmitted. If the delay is more than six bit times, there is a possibility of double byte transmission.

Method 2:

Monitor the TMRT bit of the TXxSTA register. Writes to the TXREG register can be performed once the TMRT bit is set, indicating that the Transmit Shift Register (TSR) is empty. This work around can be applied if back-to-back transmissions are not necessary.

Affected Silicon Revisions

A1	A2	A4
X	X	—

1.10 Module: Windowed Watchdog Timer (WWDT)

1.10.1 Window Operation in Doze Mode

When enabling the Windowed operation mode in Doze mode, a window violation error is issued even though the window is open and armed. This condition occurs only when the window size is set to a value other than 100% open.

Work around

Method 1:

Use the Windowed operation mode in any mode other than Doze. If disabling the Doze mode is not an option, use the WWDT module without enabling the window.

Method 2:

If the device is in Doze mode, perform the arming process for the window in Normal mode and return to the Doze mode.

Method 3:

If there is an Interrupt Service Routine (ISR) in the application code, the arming within the window can be done inside the ISR with the ROI bit of the CPUDOZE register being set.

Affected Silicon Revisions

A1	A2	A4
X	—	—

1.11 Module: Device Configuration

1.11.1 PWRTS[1] Power-up Timer Selection Not Implemented

Bit 2 of PWRTS[1:0] in the CONFIG2 register is not functional. This bit is the upper bit of the Power-Up Timer Selection bits, PWRTS[1:0]. This means that the functions selected by PWRTS = 11 and PWRTS = 10 are not available.

Work around

The other functions selected by PWRTS = 01 and PWRTS = 00 are available.

Affected Silicon Revisions

A1	A2	A4
X	—	—

2. Data Sheet Clarifications

The following typographic corrections and clarifications are to be noted for the latest version of the device data sheet (DS40001985C):

Note:

Corrections are shown in **bold**. Where possible, the original bold text formatting has been removed for clarity.

2.1 None

There are no known data sheet clarifications as of this publication date.

3. **Appendix A: Revision History**

Doc Rev.	Date	Comments
D	03/2023	Add silicon errata for A2 and A4 which includes: 1.1.2, 1.2.1, 1.6.2, 1.7.1, 1.8.1, 1.9.1, and 1.9.2; Minor editorial updates.
C	11/2020	Updating Electrical Spec. 1.3.1 description and added 1.3.2 Electrical Spec. silicon issue; Other minor corrections.
B	07/2018	Fixed typo in Table 1.
A	07/2018	Initial document release.

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SYST-10QPXN700 - ERRATA - PIC16(L)F18426/46 Family Silicon Errata and Data Sheet Clarification

Affected Catalog Part Numbers(CPN)

PIC16F18426-E/JQ
PIC16F18426-E/JQVAO
PIC16F18426-E/P
PIC16F18426-E/SL
PIC16F18426-E/ST
PIC16F18426-E/STVAO
PIC16F18426-I/JQ
PIC16F18426-I/P
PIC16F18426-I/SL
PIC16F18426-I/ST
PIC16F18426-I/STVAO
PIC16F18426T-E/JQVAO
PIC16F18426T-E/MLV02
PIC16F18426T-E/STVAO
PIC16F18426T-I/JQ
PIC16F18426T-I/SL
PIC16F18426T-I/ST
PIC16F18426T-I/STVAO
PIC16F18446-E/GZ
PIC16F18446-E/P
PIC16F18446-E/SO
PIC16F18446-E/SS
PIC16F18446-I/GZ
PIC16F18446-I/P
PIC16F18446-I/SO
PIC16F18446-I/SS
PIC16F18446T-E/GZ
PIC16F18446T-I/GZ
PIC16F18446T-I/SO
PIC16F18446T-I/SS
PIC16LF18426-E/JQ
PIC16LF18426-E/JQVAO
PIC16LF18426-E/P
PIC16LF18426-E/SL
PIC16LF18426-E/ST
PIC16LF18426-I/JQ
PIC16LF18426-I/P
PIC16LF18426-I/SL
PIC16LF18426-I/ST
PIC16LF18426T-E/JQVAO
PIC16LF18426T-I/JQ
PIC16LF18426T-I/SL

PIC16LF18426T-I/ST
PIC16LF18446-E/GZ
PIC16LF18446-E/GZVAO
PIC16LF18446-E/P
PIC16LF18446-E/SO
PIC16LF18446-E/SS
PIC16LF18446-E/SSVAO
PIC16LF18446-I/GZ
PIC16LF18446-I/P
PIC16LF18446-I/SO
PIC16LF18446-I/SS
PIC16LF18446T-E/GZ
PIC16LF18446T-E/GZVAO
PIC16LF18446T-E/SSVAO
PIC16LF18446T-I/GZ
PIC16LF18446T-I/GZC01
PIC16LF18446T-I/SO
PIC16LF18446T-I/SS