



## Product Change Notification / SYST-28TLEH778

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**Date:**

01-Dec-2022

**Product Category:**

Digital Temperature Sensors

**PCN Type:**

Document Change

**Notification Subject:**

Data Sheet - EMC1412 Data Sheet

**Affected CPNs:**

[SYST-28TLEH778\\_Affected\\_CPN\\_12012022.pdf](#)

[SYST-28TLEH778\\_Affected\\_CPN\\_12012022.csv](#)

**Notification Text:**

SYST-28TLEH778

Microchip has released a new Datasheet for the EMC1412 Data Sheet of devices. If you are using one of these devices please read the document located at [EMC1412 Data Sheet](#).

**Notification Status:** Final

**Description of Change:** • Document converted to Microchip format • Updated Package Drawings in Section 7.1 "Package Marking Information"

**Impacts to Data Sheet:** None

**Change Implementation Status:** Complete

**Date Document Changes Effective:** 01 Dec 2022

**NOTE:** Please be advised that this is a change to the document only the product has not been changed.

**Markings to Distinguish Revised from Unrevised Devices:** N/A

## Attachments:

[EMC1412 Data Sheet](#)

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## Multiple Channel 1°C Temperature Sensor with Beta Compensation

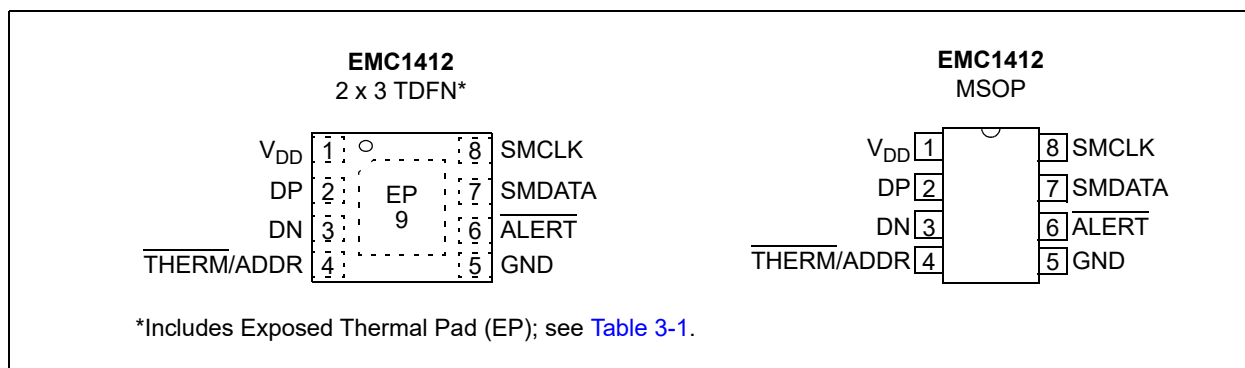
### Features

- Programmable SMBus Address
- Support for diodes requiring the BJT/transistor model including advanced processor geometries
- Automatically determines external diode type and optimal settings
- Resistance Error Correction
- External Temperature Monitor:
  - $\pm 1^{\circ}\text{C}$  Maximum Accuracy ( $+20^{\circ}\text{C} < T_{\text{DIODE}} < +110^{\circ}\text{C}$ )
  - $0.125^{\circ}\text{C}$  resolution
  - Supports up to 2.2 nF Diode Filter Capacitor
- Internal Temperature Monitor:
  - $\pm 1^{\circ}\text{C}$  Accuracy
  - $0.125^{\circ}\text{C}$  Resolution
- 3.3V Supply Voltage
- Programmable temperature limits for  $\overline{\text{ALERT}}$  and  $\overline{\text{THERM}}$
- Available in small 8-pin 2 mm x 3 mm TDFN RoHS compliant package
- Available in small 8-pin MSOP RoHS compliant package

### Applications

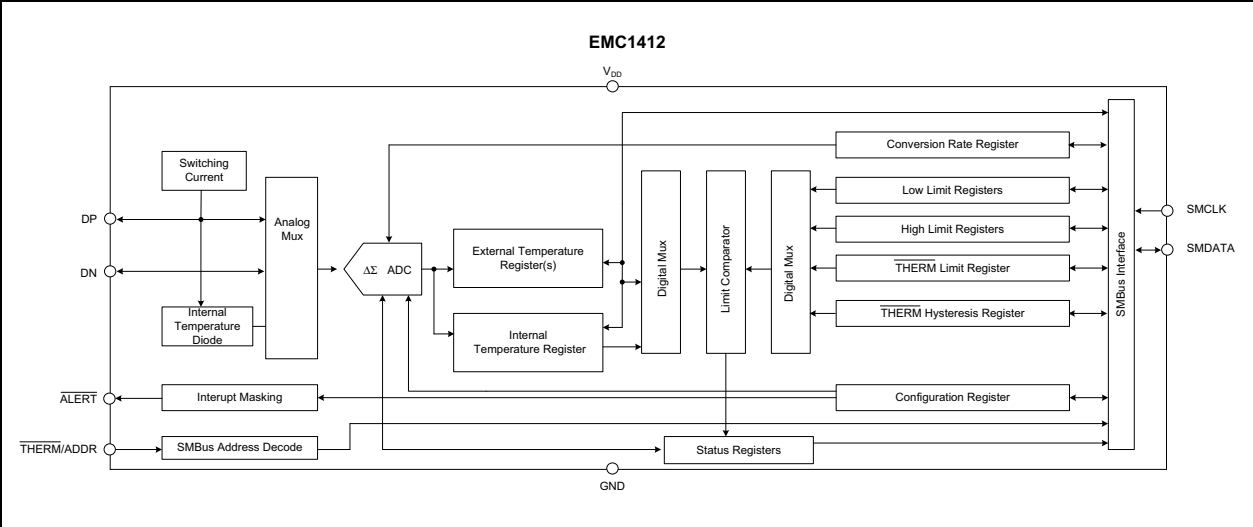
- Notebook Computers
- Desktop Computers
- Industrial
- Embedded Applications

### Package Type



# EMC1412

## Block Diagram



## 1.0 ELECTRICAL CHARACTERISTICS

### Absolute Maximum Ratings<sup>(†)</sup>

Supply Voltage ( $V_{DD}$ ) .....	-0.3V to +4.0V
Voltage on 5V tolerant pins ( $V_{5VT\_PIN}$ ).....	-0.3V to +5.5V
Voltage on 5V tolerant pins ( $ V_{5VT\_PIN} - V_{DD} $ ) (Note).....	0V to +3.6V
Voltage on any other pin to Ground .....	-0.3V to ( $V_{DD} + 0.3V$ )
ESD Rating, All pins HBM.....	2000V
Operating Temperature Range.....	-40°C to +125°C
Storage Temperature Range.....	-55°C to +150°C
Lead Temperature Range .....	Refer to JEDEC Spec. J-STD-020

**Note:** For the 5V tolerant pins that have a pull-up resistor (SMCLK, SMDATA, ALERT, and THERM), the pull-up voltage must not exceed 3.6V when the device is unpowered.

**Note:** † **Notice:** Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure above maximum rating conditions for extended periods may affect device reliability.

**TABLE 1-1: DC CHARACTERISTICS**

<b>Electrical Characteristics:</b> Unless otherwise specified, $3.0V \leq V_{DD} \leq 3.6V$ at $-40^\circ C \leq T_A \leq +125^\circ C$ , all typical values are at $T_A = 27^\circ C$ .						
Characteristic	Symbol	Min.	Typ.	Max.	Unit	Conditions
<b>DC Power</b>						
Supply Voltage	$V_{DD}$	3.0	3.3	3.6	V	—
Supply Current	$I_{DD}$	—	430	850	$\mu A$	1 conversion/second, dynamic averaging disabled
		—	930	1200	$\mu A$	4 conversions/second, dynamic averaging enabled
		—	1120	—	$\mu A$	$\geq 16$ conversions/second, dynamic averaging enabled
Standby Supply Current	$I_{DD\_OS}$	—	170	230	$\mu A$	Device in Standby mode, no SMBus communications, ALERT and THERM pins not asserted.
<b>Internal Temperature Monitor</b>						
Temperature Accuracy	—	—	$\pm 0.25$	$\pm 1$	$^\circ C$	$-5^\circ C < T_A < +100^\circ C$
		—	—	$\pm 2$	$^\circ C$	$-40^\circ C < T_A < +125^\circ C$
Temperature Resolution	—	—	0.125	—	$^\circ C$	—
<b>External Temperature Monitor</b>						
Temperature Accuracy	—	—	$\pm 0.25$	$\pm 1$	$^\circ C$	$+20^\circ C < T_{DIODE} < +110^\circ C$ $0^\circ C < T_A < +100^\circ C$
		—	$\pm 0.5$	$\pm 2$	$^\circ C$	$-40^\circ C < T_{DIODE} < +127^\circ C$
Temperature Resolution	—	—	0.125	—	$^\circ C$	—

# EMC1412

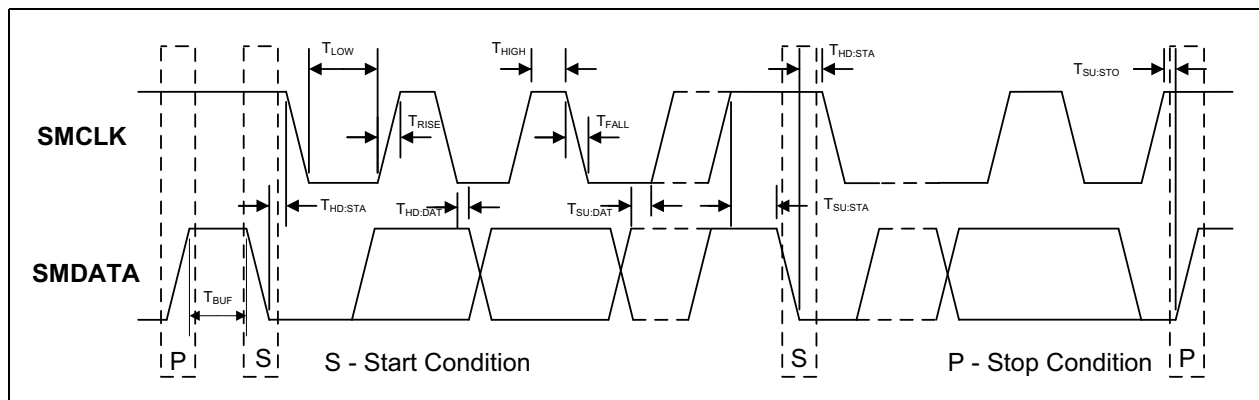
**TABLE 1-1: DC CHARACTERISTICS (CONTINUED)**

<b>Electrical Characteristics:</b> Unless otherwise specified, $3.0V \leq V_{DD} \leq 3.6V$ at $-40^{\circ}C \leq T_A \leq +125^{\circ}C$ , all typical values are at $T_A = 27^{\circ}C$ .						
Characteristic	Symbol	Min.	Typ.	Max.	Unit	Conditions
<b>Timing and Capacitive Filter</b>						
Conversion Time all Channels	$t_{CONV}$	—	190	—	ms	Default settings
Capacitive Filter	$C_{FILTER}$	—	2.2	2.7	nF	Connected across external diode
Resistance Error Correction	$R_{SERIES}$	—	—	100	$\Omega$	In series with DP and DN lines
<b>ALERT and THERM Pins</b>						
Output Low Voltage	$V_{OL}$	0.4	—	—	V	$I_{SINK} = 8\text{ mA}$
Leakage Current	$I_{LEAK}$	—	—	$\pm 5$	$\mu A$	ALERT and THERM pins Device powered or unpowered $T_A < +85^{\circ}C$ Pull-up voltage $\leq 3.6V$

**TABLE 1-2: SMBUS TIMING SPECIFICATION**

**Electrical Characteristics:** Unless otherwise specified,  $3.0V \leq V_{DD} \leq 3.6V$  at  $-40^{\circ}C \leq T_A \leq +125^{\circ}C$ , all typical values are at  $T_A = 27^{\circ}C$ .

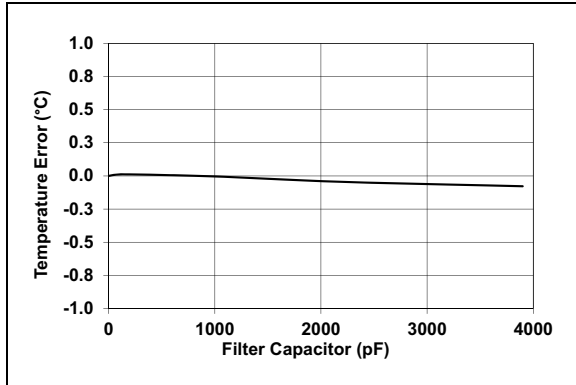
Characteristic	Symbol	Min.	Typ.	Max.	Unit	Conditions
<b>SMBus Interface</b>						
Input High Voltage	$V_{IH}$	2.0	—	$V_{DD}$	V	5V Tolerant
Input Low Voltage	$V_{IL}$	-0.3	—	0.8	V	5V Tolerant
Leakage Current	$I_{LEAK}$	—	—	$\pm 5$	$\mu A$	Powered or unpowered $T_A < +85^{\circ}C$
Hysteresis	—	—	420	—	mV	—
Input Capacitance	$C_{IN}$	—	5	—	pF	—
Output Low Sink Current	$I_{OL}$	8.2	—	15	mA	SMDATA = 0.4V
<b>SMBus Timing</b>						
Clock Frequency	$f_{SMB}$	10	—	400	kHz	—
Spike Suppression	$t_{SP}$	—	—	50	ns	—
Bus free Time Start to Stop	$t_{BUF}$	1.3	—	—	$\mu s$	—
Hold Time: Start	$t_{HD:STA}$	0.6	—	—	$\mu s$	—
Setup Time: Start	$t_{SU:STA}$	0.6	—	—	$\mu s$	—
Setup Time: Stop	$t_{SU:STP}$	0.6	—	—	$\mu s$	—
Data Hold Time	$t_{HD:DAT}$	0	—	—	$\mu s$	When transmitting to the master
Data Hold Time	$t_{HD:DAT}$	0.3	—	—	$\mu s$	When receiving from the master
Data Setup Time	$t_{SU:DAT}$	100	—	—	ns	—
Clock Low Period	$t_{LOW}$	1.3	—	—	$\mu s$	—
Clock High Period	$t_{HIGH}$	0.6	—	—	$\mu s$	—
Clock/Data Fall time	$t_{FALL}$	—	—	300	ns	Min = $20 + 0.1C_{LOAD}$ ns
Clock/Data Rise time	$t_{RISE}$	—	—	300	ns	Min = $20 + 0.1C_{LOAD}$ ns
Capacitive Load	$C_{LOAD}$	—	—	400	pF	per bus line



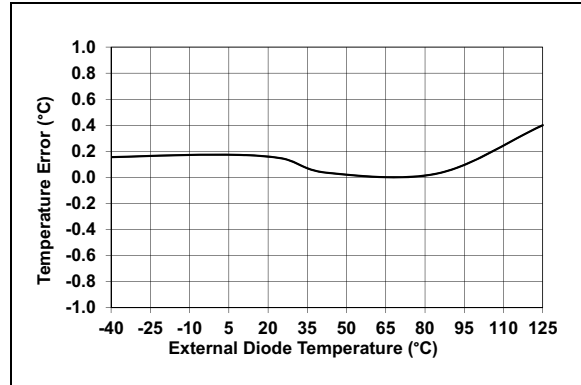
**FIGURE 1-1: SMBus Timing.**

## 2.0 TYPICAL PERFORMANCE CURVES

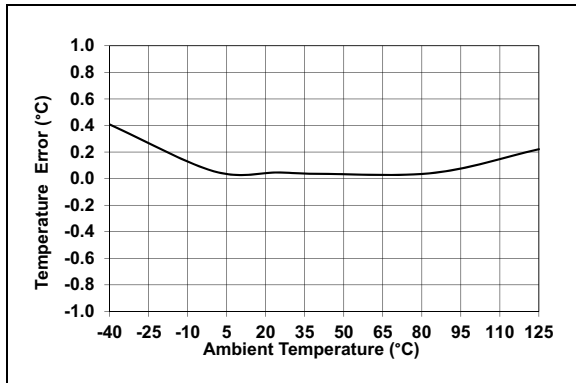
**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.



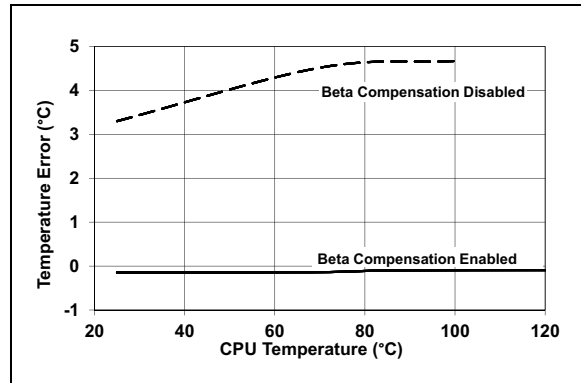
**FIGURE 2-1:** Temperature Error vs. Filter Capacitor (2N3904,  $T_A = 27^\circ\text{C}$ ,  $T_{DIODE} = 27^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ ).



**FIGURE 2-3:** Temperature Error vs. External Diode Temperature (2N3904,  $T_{DIODE} = 42.5^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ ).

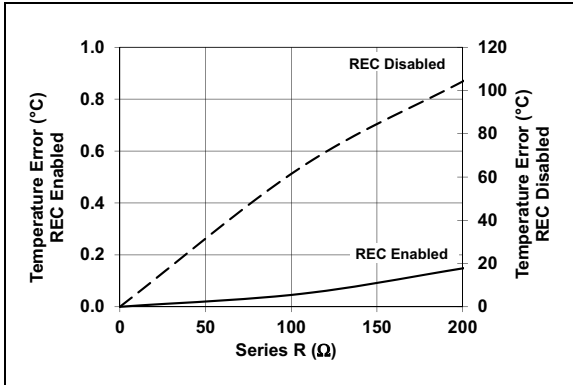


**FIGURE 2-2:** Temperature Error vs. Ambient Temperature (2N3904,  $T_A = 42.5^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ ).

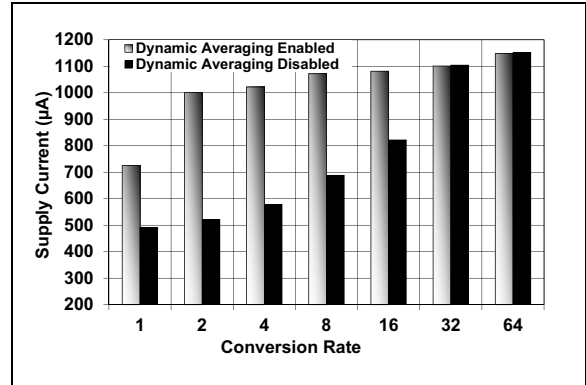


**FIGURE 2-4:** Temperature Error vs. CPU Temperature; Typical 65 nm CPU from Major Vendor ( $T_A = 27^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ ,  $BETA = 011$ ,  $C_{FILTER} = 470\text{ pF}$ ).

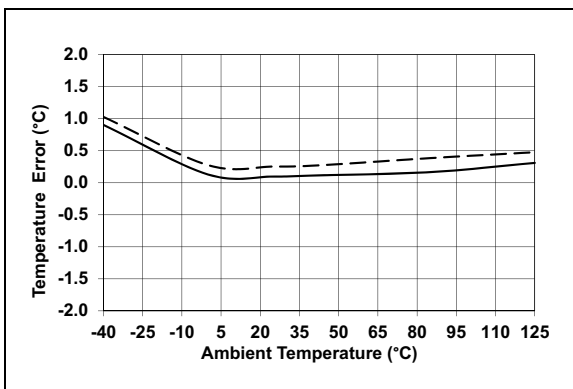




**FIGURE 2-5:** Temperature Error vs. Series Resistance.



**FIGURE 2-7:** Supply Current vs. Conversion Rate.



**FIGURE 2-6:** Temperature Error vs. Ambient Temperature (2N3904,  $T_A = 27^\circ\text{C}$ ,  $V_{DD} = 3.3\text{V}$ ).

# EMC1412

## 3.0 PIN FUNCTION TABLE

The descriptions of the pins are shown in the table below.

TABLE 3-1: PIN FUNCTION TABLE (Note 1)

Pin Number		Pin Name	Pin Type	Description
8-Lead MSOP	8-Lead TDFN			
1	1	V <sub>DD</sub>	Power	Power Supply
2	2	DP	AIO	External diode positive (anode) connection
3	3	DN	AIO	External diode negative (cathode) connection
4	4	THERM/ADDR	OD (5V)	THERM - Critical THERM output signal. Requires pull-up resistor. ADDR - Selects SMBus address based on pull-up resistor
5	5	GND	Power	Ground pin
6	6	ALERT	OD (5V)	Active low digital ALERT output signal. Requires pull-up resistor.
7	7	SMDATA	DIOD (5V)	SMBus Data input/output. Requires pull-up resistor.
8	8	SMCLK	DI (5V)	SMBus Clock input. Requires pull-up resistor.
—	9	EP	—	Exposed Thermal Pad. Not internally connected. Grounding is recommended.

**Note 1:** For the 5V tolerant pins that have a pull-up resistor (SMCLK, SMDATA, THERM and ALERT), the voltage difference between V<sub>DD</sub> and the pull-up voltage must never exceed 3.6V.

### 3.1 Power Pins (V<sub>DD</sub> and GND)

These pins are used to supply power to or ground the device.

### 3.2 Analog Input/Output (AIO) Pins (DP, DN)

These pins are used as inputs/outputs for analog signals.

### 3.3 Digital Input (DI) Pin (SMCLK)

This pin is used as a digital input. This pin is 5V tolerant (see Note 1).

### 3.4 Digital Input/Open-Drain Output (DIOD) Pin (SMDATA)

This pin is used as a digital input/output. When used as an output, it is open-drain and requires a pull-up resistor. This pin is 5V tolerant (see Note 1).

### 3.5 Open-Drain Digital Output (OD) Pins (THERM/ADDR, ALERT)

These pins are used as digital outputs. They are open-drain pins and require a pull-up resistor. These pins are 5V tolerant (see Note 1).

## 4.0 PRODUCT DESCRIPTION

The EMC1412 is an SMBus temperature sensor. The EMC1412 monitors one internal diode and one externally connected temperature diode.

Thermal management is performed in cooperation with a host device. This consists of the host reading the temperature data of both the external and internal temperature diodes of the EMC1412 and using that data to control the speed of one or more fans.

The EMC1412 has two levels of monitoring. The first provides a maskable ALERT signal to the host when the measured temperatures exceeds user programmable limits.

This allows the EMC1412 to be used as an independent thermal watchdog to warn the host of temperature hot spots without the direct control of the host. The second level of monitoring provides a non maskable interrupt on the THERM pin if the measured temperatures meet or exceed a second programmable limit.

The figure below shows a system level block diagram of the EMC1412.

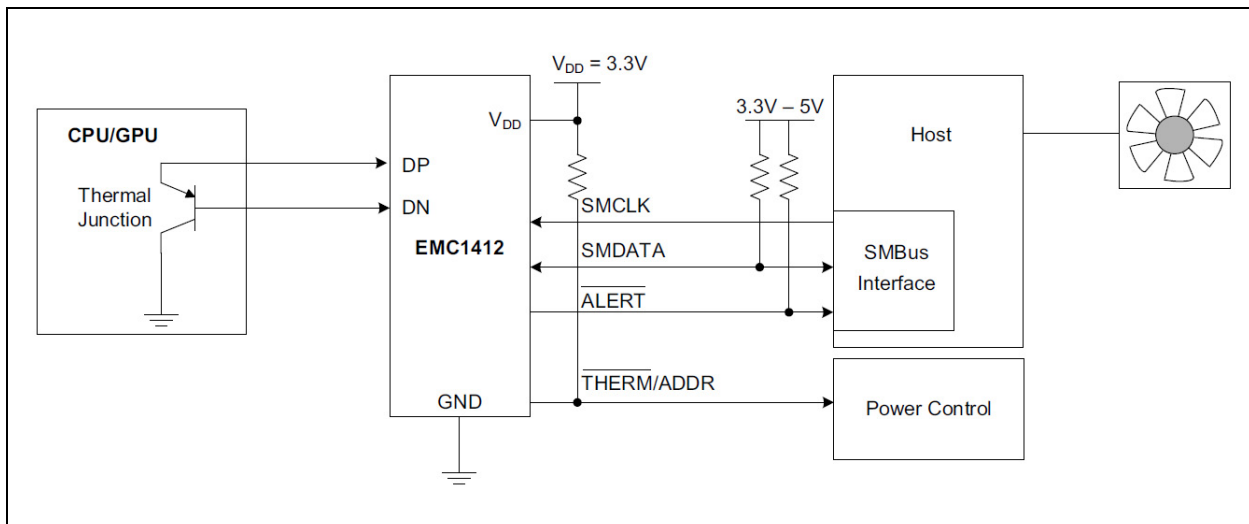


FIGURE 4-1: System Diagram.

## 4.1 Modes of Operation

The EMC1412 have two modes of operation:

- **Active (Run)** - In this mode of operation, the ADC is converting on all temperature channels at the programmed conversion rate. The temperature data is updated at the end of every conversion and the limits are checked. In Active mode, writing to the one-shot register will do nothing.
- **Standby (Stop)** - In this mode of operation, the majority of circuitry is powered down to reduce supply current. The temperature data is not updated and the limits are not checked. In this mode of operation, the SMBus is fully active and the part will return requested data. Writing to the oneshot register will enable the device to update all temperature channels. Once all the channels are updated, the device will return to the Standby mode.

### 4.1.1 CONVERSION RATES

The EMC1412 may be configured for different conversion rates based on the system requirements. The conversion rate is configured as described in [Section 6.5 "Conversion Rate Register"](#). The default conversion rate is four conversions per second.

### 4.1.2 DYNAMIC AVERAGING

Dynamic averaging causes the EMC1412 to measure the external diode channels for an extended time based on the selected conversion rate. This functionality can be disabled for increased power savings at the lower conversion rates (see [Section 6.4 "Configuration Register"](#)). When dynamic averaging is enabled, the device will automatically adjust the sampling and measurement time for the external diode channels. This allows the device to average 2x or 16x longer than the normal 11 bit operation (nominally 21ms per channel) while still maintaining the selected conversion rate.

The benefits of dynamic averaging are improved noise rejection due to the longer integration time as well as less random variation of the temperature measurement.

# EMC1412

When enabled, the dynamic averaging applies when a one-shot command is issued. The device will perform the desired averaging during the one-shot operation according to the selected conversion rate.

When enabled, the dynamic averaging will affect the average supply current based on the chosen conversion rate as shown in the table below.

**TABLE 4-1: SUPPLY CURRENT VS. CONVERSION RATE FOR EMC1412**

Conversion Rate	Average Supply Current		Averaging Factor (based on 11-bit operation)	
	Enabled (default)	Disabled	Enabled (default)	Disabled
1/16 seconds	660 $\mu$ A	430 $\mu$ A	16x	1x
1/8 sec	660 $\mu$ A	430 $\mu$ A	16x	1x
1/4 sec	660 $\mu$ A	430 $\mu$ A	16x	1x
1/2 sec	660 $\mu$ A	430 $\mu$ A	16x	1x
1/sec	660 $\mu$ A	430 $\mu$ A	16x	1x
2/sec	930 $\mu$ A	475 $\mu$ A	16x	1x
4/sec (default)	950 $\mu$ A	510 $\mu$ A	8x	1x
8/sec	1010 $\mu$ A	630 $\mu$ A	4x	1x
16/sec	1020 $\mu$ A	775 $\mu$ A	2x	1x
32/sec	1050 $\mu$ A	1050 $\mu$ A	1x	1x
64/sec	1100 $\mu$ A	1100 $\mu$ A	0.5x	0.5x

## 4.2 THERM Output

The  $\overline{\text{THERM}}$  output is asserted independently of the ALERT output and cannot be masked. Whenever any of the measured temperatures exceed the user programmed Therm Limit values for the programmed number of consecutive measurements, the  $\overline{\text{THERM}}$  output is asserted. Once it has been asserted, it will remain asserted until all measured temperatures drop below the Therm Limit minus the Therm Hysteresis (also programmable).

When the  $\overline{\text{THERM}}$  pin is asserted, the  $\overline{\text{THERM}}$  status bits will likewise be set. Reading these bits will not clear them until the  $\overline{\text{THERM}}$  pin is deasserted. Once the  $\overline{\text{THERM}}$  pin is deasserted, the  $\overline{\text{THERM}}$  status bits will be automatically cleared.

## 4.3 ALERT Output

The  $\overline{\text{ALERT}}$  pin is an open drain output and requires a pull-up resistor to  $V_{DD}$  and has two modes of operation: interrupt mode and comparator mode. The mode of the ALERT output is selected via the ALERT / COMP bit in the [Section 6.4 “Configuration Register”](#).

### 4.3.1 ALERT PIN INTERRUPT MODE

When configured to operate in interrupt mode, the  $\overline{\text{ALERT}}$  pin asserts low when an out of limit measurement ( $>$  high limit or  $<$  low limit) is detected on any diode or when a diode fault is detected. The  $\overline{\text{ALERT}}$  pin will remain asserted as long as an out-of-limit condition remains. Once the out-of-limit condition has been removed, the  $\overline{\text{ALERT}}$  pin will remain asserted until the appropriate status bits are cleared.

The  $\overline{\text{ALERT}}$  pin can be masked by setting the MASK\_ALL bit. Once the  $\overline{\text{ALERT}}$  pin has been masked, it will be de-asserted and remain de-asserted until the MASK\_ALL bit is cleared by the user. Any interrupt conditions that occur while the  $\overline{\text{ALERT}}$  pin is masked will update the Status Register normally. There are also individual channel masks (see [Section 6.10 “Channel Mask Register”](#)).

The  $\overline{\text{ALERT}}$  pin is used as an interrupt signal or as an SMBus Alert signal that allows an SMBus slave to communicate an error condition to the master. One or more  $\overline{\text{ALERT}}$  outputs can be hard-wired together.

### 4.3.2 ALERT PIN COMPARATOR MODE

When the  $\overline{\text{ALERT}}$  pin is configured to operate in comparator mode, it will be asserted if any of the measured temperatures exceeds the respective high limit. The  $\overline{\text{ALERT}}$  pin will remain asserted until all temperatures drop below the corresponding high limit minus the Therm Hysteresis value.

When the  $\overline{\text{ALERT}}$  pin is asserted in comparator mode, the corresponding high limit status bits will be set. Reading these bits will not clear them until the  $\overline{\text{ALERT}}$  pin is deasserted. Once the  $\overline{\text{ALERT}}$  pin is deasserted, the status bits will be automatically cleared.

The MASK\_ALL bit will not block the  $\overline{\text{ALERT}}$  pin in this mode; however, the individual channel masks (see [Section 6.10 “Channel Mask Register”](#)) will prevent the respective channel from asserting the  $\overline{\text{ALERT}}$  pin.

## 4.4 Temperature Measurement

The EMC1412 can monitor the temperature of one externally connected diode. The external diode channel is configured with Resistance Error Correction and Beta Compensation based on user settings and system requirements.

The device contains programmable High, Low, and Therm limits for all measured temperature channels. If the measured temperature goes below the Low limit or above the High limit, the `ALERT` pin can be asserted (based on user settings). If the measured temperature meets or exceeds the Therm Limit, the `THERM` pin is asserted unconditionally, providing two tiers of temperature detection.

### 4.4.1 BETA COMPENSATION

The EMC1412 is configured to monitor the temperature of basic diodes (e.g., 2N3904) or CPU thermal diodes. It automatically detects the type of external diode (CPU diode or diode connected transistor) and determines the optimal setting to reduce temperature errors introduced by beta variation. Compensating for this error is also known as implementing the transistor or BJT model for temperature measurement.

For discrete transistors configured with the collector and base shorted together, the beta is generally sufficiently high such that the percent change in beta variation is very small. For example, a 10% variation in beta for two forced emitter currents with a transistor whose ideal beta is 50 would contribute approximately 0.25°C error at 100°C. However for substrate transistors where the base-emitter junction is used for temperature measurement and the collector is tied to the substrate, the proportional beta variation will cause large error. For example, a 10% variation in beta for two forced emitter currents with a transistor whose ideal beta is 0.5 would contribute approximately 8.25°C error at 100°C.

### 4.4.2 RESISTANCE ERROR CORRECTION (REC)

Parasitic resistance in series with the external diodes will limit the accuracy obtainable from temperature measurement devices. The voltage developed across this resistance by the switching diode currents cause the temperature measurement to read higher than the true temperature. Contributors to series resistance are PCB trace resistance, on die (i.e. on the processor) metal resistance, bulk resistance in the base and emitter of the temperature transistor. Typically, the error caused by series resistance is +0.7°C per ohm. The EMC1412 automatically corrects up to 100 ohms of series resistance.

### 4.4.3 PROGRAMMABLE EXTERNAL DIODE IDEALITY FACTOR

The EMC1412 is designed for external diodes with an ideality factor of 1.008. Not all external diodes, processor or discrete, will have this exact value. This variation of the ideality factor introduces error in the temperature measurement which must be corrected for. This correction is typically done using programmable offset registers. Since an ideality factor mismatch introduces an error that is a function of temperature, this correction is only accurate within a small range of temperatures. To provide maximum flexibility to the user, the EMC1412 provides a 6-bit register for each external diode where the ideality factor of the diode used is programmed to eliminate errors across all temperatures.

**Note:** When monitoring a substrate transistor or CPU diode and beta compensation is enabled, the Ideality Factor should not be adjusted. Beta Compensation automatically corrects for most ideality errors.

## 4.5 Diode Faults

The EMC1412 detects an open on the DP and DN pins, and a short across the DP and DN pins. For each temperature measurement made, the device checks for a diode fault on the external diode channel(s). When a diode fault is detected, the `ALERT` pin asserts (unless masked, see [Section 6.11 “Consecutive ALERT Register”](#) and the temperature data reads 00h in the MSB and LSB registers (note: the low limit will not be checked). A diode fault is defined as one of the following: an open between DP and DN, a short from  $V_{DD}$  to DP, or a short from  $V_{DD}$  to DN.

If a short occurs across DP and DN or a short occurs from DP to GND, the low limit status bit is set and the `ALERT` pin asserts (unless masked). This condition is indistinguishable from a temperature measurement of 0.000°C (-64°C in extended range) resulting in temperature data of 00h in the MSB and LSB registers.

If a short from DN to GND occurs (with a diode connected), temperature measurements will continue as normal, with no alerts.

## 4.6 Consecutive Alerts

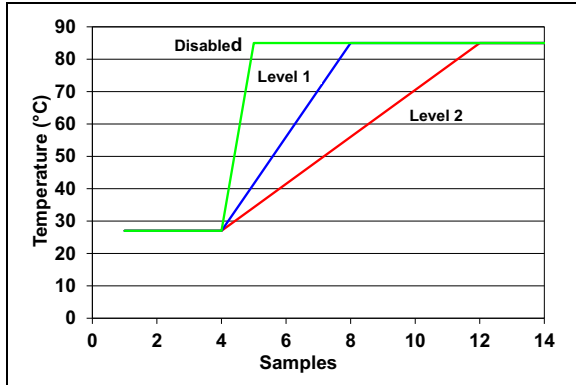
The EMC1412 contain multiple consecutive alert counters. One set of counters applies to the `ALERT` pin and the second set of counters applies to the `THERM` pin. Each temperature measurement channel has a separate consecutive alert counter for each of the `ALERT` and `THERM` pins. All counters are user programmable and determine the number of consecutive measurements that a temperature channel(s) must be out-of-limit or reporting a diode fault before the corresponding pin is asserted.

# EMC1412

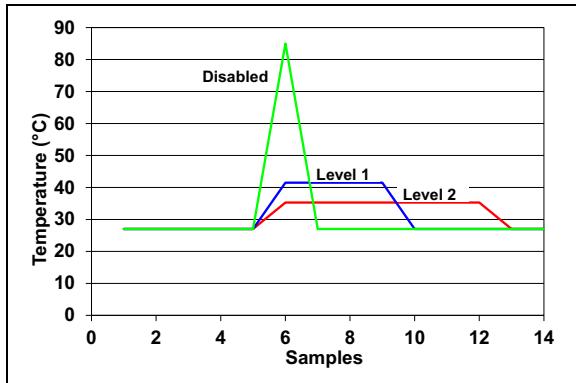
See [Section 6.11 “Consecutive ALERT Register”](#) for more details on the consecutive alert function.

## 4.7 Digital Filter

To reduce the effect of noise and temperature spikes on the reported temperature, the External Diode channel uses a programmable digital filter. This filter can be configured as Level 1, Level 2, or Disabled (default) (see [Section 6.14 “Filter Control Register”](#)). The typical filter performance is shown in the figures below.



**FIGURE 4-2:** Temperature Filter Step Response.



**FIGURE 4-3:** Temperature Filter Impulse Response.

## 4.8 Temperature Measurement Results and Data

The temperature measurement results are stored in the internal and external temperature registers. These are then compared with the values stored in the high and low limit registers. Both external and internal temperature measurements are stored in 11-bit format with the eight (8) most significant bits stored in a high byte register and the three (3) least significant bits stored in the three (3) MSB positions of the low byte register. All other bits of the low byte register are set to zero.

The EMC1412 has two selectable temperature ranges. The default range is from 0°C to +127°C and the temperature is represented as binary number able to report a temperature from 0°C to +127.875°C in 0.125°C steps.

The extended range is an extended temperature range from -64°C to +191°C. The data format is a binary number offset by 64°C. The extended range is used to measure temperature diodes with a large known offset (such as AMD processor diodes) where the diode temperature plus the offset would be equivalent to a temperature higher than +127°C.

The table below shows the default and extended range formats.

**TABLE 4-2: TEMPERATURE DATA FORMAT**

Temperature (°C)	Default Range (0°C to +127°C)	Extended Range (-64°C to +191°C)
Diode Fault	000 0000 0000	000 0000 0000
-64	000 0000 0000	000 0000 0000 (Note 2)
-1	000 0000 0000	001 1111 1000
0	000 0000 0000 (Note 1)	010 0000 0000
0.125	000 0000 0001	010 0000 0001
1	000 0000 1000	010 0000 1000
64	010 0000 0000	100 0000 0000
65	010 0000 1000	100 0000 1000
127	011 1111 1000	101 1111 1000
127.875	011 1111 1111	101 1111 1111
128	011 1111 1111 (Note 3)	110 0000 0000
190	011 1111 1111	111 1111 0000
191	011 1111 1111	111 1111 1000
≥ 191.875	011 1111 1111	111 1111 1111 (Note 4)

- Note 1:** For default range, all temperatures < 0°C will be reported as 0°C.
- Note 2:** For extended range, all temperatures < -64°C will be reported as -64°C.
- Note 3:** For default range, all temperatures > +127.875°C will be reported as +127.875°C.
- Note 4:** For extended range, all temperatures > +191.875°C will be reported as +191.875°C.

## 4.9 External Diode Connections

The EMC1412 can be configured to measure a CPU substrate transistor, a discrete 2N3904 thermal diode, or an AMD processor diode. The diodes can be connected as indicated in [Figure 4-4](#).

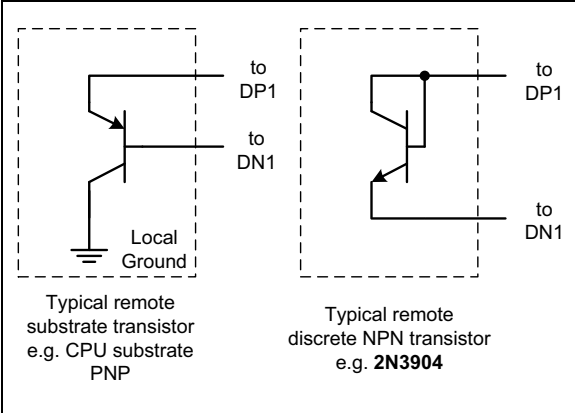


FIGURE 4-4: Diode Configuration.

# EMC1412

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NOTES:



## 5.0 SYSTEM MANAGEMENT BUS INTERFACE PROTOCOL

protocol between a computer host and its peripheral devices. A detailed timing diagram is shown in the figure below.

### 5.1 Communications Protocol

The EMC1412 communicates with a host controller, such as a Microchip embedded controller, through the SMBus. The SMBus is a two-wire serial communication

For the first 15 ms after power-up the device may not respond to SMBus communications.

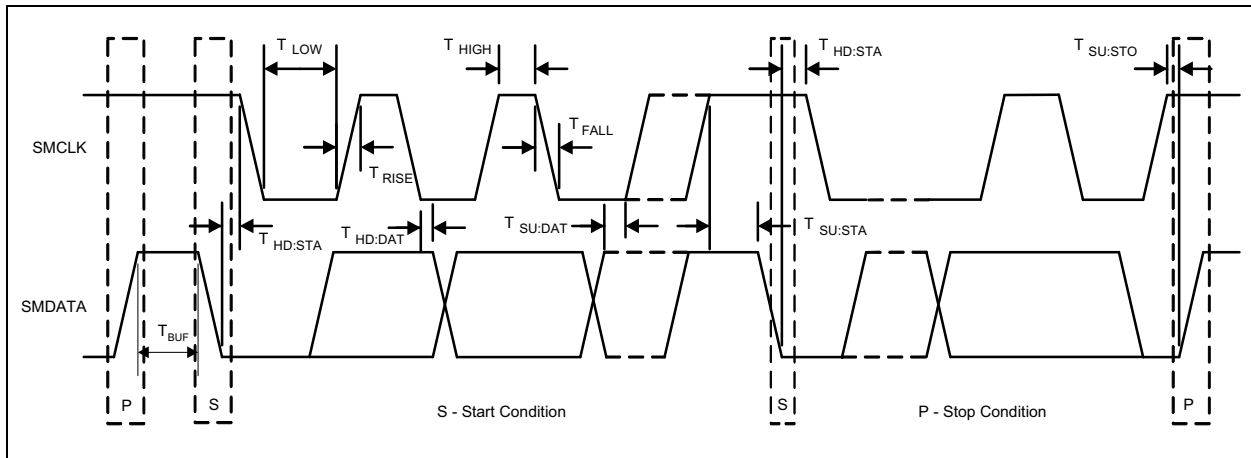


FIGURE 5-1: SMBus Timing Diagram.

### 5.2 SMBus Start Bit

The SMBus Start bit is defined as a transition of the SMBus Data line from a logic '1' state to a logic '0' state while the SMBus Clock line is in a logic '1' state.

### 5.3 SMBus Address and RD/WR Bit

The SMBus Address Byte consists of the 7-bit client address followed by the RD / WR indicator bit. If this RD / WR bit is a logic '0', the SMBus Host is writing data to the client device. If this RD / WR bit is a logic '1', the SMBus Host is reading data from the client device.

The EMC1412-A SMBus slave address is determined by the pull-up resistor on the THERM pin as shown in the table below.

The Address decode is performed by pulling known currents from  $V_{DD}$  through the external resistor causing the pin voltage to drop based on the respective current / resistor relationship. This pin voltage is compared against a threshold that determines the value of the pull-up resistor.

TABLE 5-1: SMBUS ADDRESS DECODE

Pull-Up Resistor on THERM Pin ( $\pm 5\%$ )	SMBus Address
4.7 k $\Omega$	1111_100 (r/w) b
6.8 k $\Omega$	1011_100 (r/w) b
10 k $\Omega$	1001_100 (r/w) b
15 k $\Omega$	1101_100 (r/w) b
22 k $\Omega$	0011_100 (r/w) b
33 k $\Omega$	0111_100 (r/w) b

**Note 1:** The EMC1412-1 SMBus address is hardcoded to 1001\_100 (r/w).

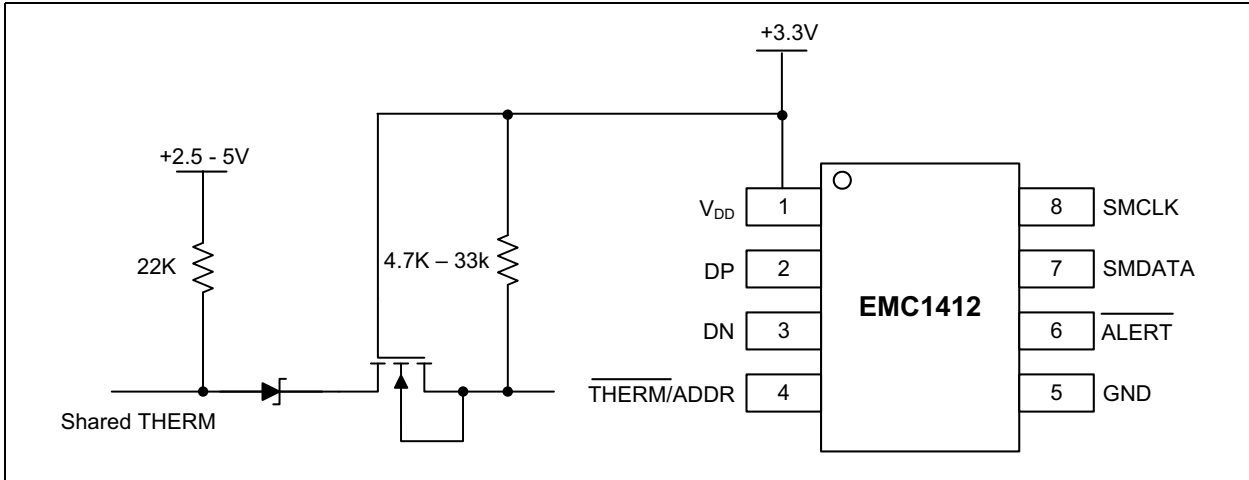
**2:** The EMC1412-2 SMBus address is hardcoded to 1001\_101 (r/w).

### 5.4 THERM Pin Considerations

Because of the decode method used to determine the SMBus Address, it is important that the pull-up resistance on the THERM pin be within the tolerances shown in the table above. Additionally, the pull-up resistor on the THERM pin must be connected to the same 3.3V supply that drives the  $V_{DD}$  pin.

For 15 ms after power up, the THERM pin must not be pulled low or the SMBus address will not be decoded properly. If the system requirements do not permit these conditions, the THERM pin must be isolated from its hard-wired OR'd bus during this time.

One method of isolating this pin is shown in Figure 5-2.



**FIGURE 5-2:** Isolating THERM Pin.

## 5.5 SMBus Data Bytes

All SMBus Data bytes are sent most significant bit first and composed of 8-bits of information.

## 5.6 SMBus ACK and NACK Bits

The SMBus client will acknowledge all data bytes that it receives. This is done by the client device pulling the SMBus data line low after the 8th bit of each byte that is transmitted. This applies to the Write Byte protocol.

The Host will NACK (not acknowledge) the last data byte to be received from the client by holding the SMBus data line high after the 8th data bit has been sent.

## 5.7 SMBus Stop Bit

The SMBus Stop bit is defined as a transition of the SMBus Data line from a logic '0' state to a logic '1' state while the SMBus clock line is in a logic '1' state. When the device detects an SMBus Stop bit and it has been communicating with the SMBus protocol, it will reset its client interface and prepare to receive further communications.

## 5.8 SMBus Timeout

The EMC1412 supports SMBus Timeout. If the clock line is held low for longer than 30 ms, the device will reset its SMBus protocol. This function can be enabled by setting the TIMEOUT bit in the Consecutive Alert Register (see [Section 4.6 "Consecutive Alerts"](#)).

## 5.9 SMBus and I2C Compatibility

The EMC1412 is compatible with SMBus and I2C. The major differences between SMBus and I2C devices are highlighted here. For more information, refer to the

SMBus 2.0 and I2C specifications. For information on using the EMC1412 in an I2C system, refer to AN 14.0 Dedicated Slave Devices in I2C Systems.

1. EMC1412 supports I2C fast mode at 400kHz. This covers the SMBus max time of 100kHz.
2. Minimum frequency for SMBus communications is 10kHz.
3. The SMBus client protocol will reset if the clock is held at a logic '0' for longer than 30ms. This timeout functionality is disabled by default in the EMC1412 and can be enabled by writing to the TIMEOUT bit. I2C does not have a timeout.
4. I2C devices do not support the Alert Response Address functionality (which is optional for SMBus).

Attempting to communicate with the EMC1412 SMBus interface with an invalid slave address or invalid protocol will result in no response from the device and will not affect its register contents. Stretching of the SMCLK signal is supported, provided other devices on the SMBus control the timing.

## 5.10 SMBus Protocols

The device supports Send Byte, Read Byte, Write Byte, Receive Byte, and the Alert Response Address as valid protocols as shown below. All of the below protocols use the convention in the table below.

**TABLE 5-2: PROTOCOL FORMAT**

Data Sent to Device	Data Sent to the Host
# of bits sent	# of bits sent

### 5.10.1 WRITE BYTE

The Write Byte is used to write one byte of data to the registers, as shown in [Table 5-3](#).

# EMC1412

**TABLE 5-3: WRITE BYTE PROTOCOL**

START	Slave Address	WR	ACK	Register Address	ACK	Register Data	ACK	STOP
1 → 0	YYYY_YYY	0	0	XXh	0	XXh	0	0 → 1

## 5.10.2 READ BYTE

The Read Byte protocol is used to read one byte of data from the registers as shown in the table below.

**TABLE 5-4: READ BYTE PROTOCOL**

START	Slave Address	WR	ACK	Register Address	ACK	START	Slave Address	RD	ACK	Register Data	NACK	STOP
1 → 0	YYYY_YYY	0	0	XXh	0	1 → 0	YYYY_YYY	1	0	XX	1	0 → 1

## 5.10.3 SEND BYTE

The Send Byte protocol is used to set the internal address register pointer to the correct address location. No data is transferred during the Send Byte protocol as shown in the table below.

**TABLE 5-5: SEND BYTE PROTOCOL**

START	Slave Address	WR	ACK	Register Address	ACK	STOP
1 → 0	YYYY_YYY	0	0	XXh	0	0 → 1

## 5.10.4 RECEIVE BYTE

The Receive Byte protocol is used to read data from a register when the internal register address pointer is known to be at the right location (e.g. set via Send Byte). This is used for consecutive reads of the same register as shown in the table below.

**TABLE 5-6: RECEIVE BYTE PROTOCOL**

START	Slave Address	RD	ACK	Register Data	NACK	STOP
1 → 0	YYYY_YYY	1	0	XXh	1	0 → 1

## 5.11 Alert Response Address

The  $\overline{\text{ALERT}}$  output can be used as a processor interrupt or as an SMBus Alert.

When it detects that the  $\overline{\text{ALERT}}$  pin is asserted, the host will send the Alert Response Address (ARA) to the general address of 0001\_100xb. All devices with active interrupts will respond with their client address as shown in the table below.

**TABLE 5-7: ALERT RESPONSE ADDRESS PROTOCOL**

START	Alert Response Address	RD	ACK	Device Address	NACK	STOP
1 → 0	0001_100	1	0	YYYY_YYY	1	0 → 1

# EMC1412

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The EMC1412 will respond to the ARA in the following way:

1. Send Slave Address and verify that full slave address was sent (i.e. the SMBus communication from the device was not prematurely stopped due to a bus contention event).
2. Set the MASK bit to clear the  $\overline{\text{ALERT}}$  pin.

**Note:** The ARA does not clear the Status Register and if the MASK bit is cleared prior to the Status Register being cleared, the  $\overline{\text{ALERT}}$  pin will be reasserted.

## 6.0 REGISTER DESCRIPTION

The registers shown in the table below are accessible through the SMBus. An entry of “-” indicates that the bit is not used and will always read ‘0’.

**TABLE 6-1: REGISTER SET IN HEXADECIMAL ORDER**

Register Address	R/W	Register Name	Function	Default Value
00h	R	Internal Diode Data High Byte	Stores the integer data for the Internal Diode.	00h
01h	R	External Diode Data High Byte	Stores the integer data for External Diode.	00h
02h	R/C	Status	Stores the status bits for the Internal Diode and External Diodes.	00h
03h	R/W	Configuration	Controls the general operation of the device (mirrored at address 09h).	00h
04h	R/W	Conversion Rate	Controls the conversion rate for updating temperature data (mirrored at address 0Ah).	06h (4/sec)
05h	R/W	Internal Diode High Limit	Stores the 8-bit high limit for the Internal Diode (mirrored at address 0Bh).	55h (+85°C)
06h	R/W	Internal Diode Low Limit	Stores the 8-bit low limit for the Internal Diode (mirrored at address 0Ch).	00h (0°C)
07h	R/W	External Diode High Limit High Byte	Stores the integer portion of the high limit for External Diode (mirrored at register 0Dh).	55h (+85°C)
08h	R/W	External Diode Low Limit High Byte	Stores the integer portion of the low limit for External Diode (mirrored at register 0Eh).	00h (0°C)
09h	R/W	Configuration	Controls the general operation of the device (mirrored at address 03h).	00h
0Ah	R/W	Conversion Rate	Controls the conversion rate for updating temperature data (mirrored at address 04h).	06h (4/sec)
0Bh	R/W	Internal Diode High Limit	Stores the 8-bit high limit for the Internal Diode (mirrored at address 05h).	55h (+85°C)
0Ch	R/W	Internal Diode Low Limit	Stores the 8-bit low limit for the Internal Diode (mirrored at address 06h).	00h (0°C)
0Dh	R/W	External Diode High Limit High Byte	Stores the integer portion of the high limit for External Diode (mirrored at register 07h).	55h (+85°C)
0Eh	R/W	External Diode Low Limit High Byte	Stores the integer portion of the low limit for External Diode (mirrored at register 08h).	00h (0°C)
0Fh	W	One-Shot	A write to this register initiates a one-shot update.	00h
10h	R	External Diode Data Low Byte	Stores the fractional data for External Diode.	00h
11h	R/W	Scratchpad	Scratchpad register for software compatibility.	00h
12h	R/W	Scratchpad	Scratchpad register for software compatibility.	00h
13h	R/W	External Diode High Limit Low Byte	Stores the fractional portion of the high limit for External Diode.	00h
14h	R/W	External Diode Low Limit Low Byte	Stores the fractional portion of the low limit for External Diode.	00h
19h	R/W	External Diode Therm Limit	Stores the 8-bit critical temperature limit for External Diode.	55h (+85°C)
1Fh	R/W	Channel Mask Register	Controls the masking of individual channels.	00h
20h	R/W	Internal Diode Therm Limit	Stores the 8-bit critical temperature limit for the Internal Diode.	55h (+85°C)

**TABLE 6-1: REGISTER SET IN HEXADECIMAL ORDER (CONTINUED)**

Register Address	R/W	Register Name	Function	Default Value
21h	R/W	Therm Hysteresis	Stores the 8-bit hysteresis value that applies to all Therm limits.	0Ah (10°C)
22h	R/W	Consecutive ALERT	Controls the number of out-of-limit conditions that must occur before an interrupt is asserted.	70h
25h	R/W	External Diode Beta Configuration	Stores the Beta Compensation circuitry settings for External Diode.	08h
27h	R/W	External Diode Ideality Factor	Stores the ideality factor for External Diode.	12h (1.008)
29h	R	Internal Diode Data Low Byte	Stores the fractional data for the Internal Diode.	00h
40h	R/W	Filter Control	Controls the digital filter setting for the External Diode channel.	00h
FDh	R	Product ID (DSTEMP)	Stores a fixed value that identifies the device.	21h
FEh	R	Manufacturer ID	Stores a fixed value that represents Microchip.	5Dh
FFh	R	Revision	Stores a fixed value that represents the revision number.	04h

## 6.1 Data Read Interlock

When any temperature channel high byte register is read, the corresponding low byte is copied into an internal "shadow" register. The user is free to read the low byte at any time and be guaranteed that it will correspond to the previously read high byte. Regardless if the low byte is read or not, reading from the same high byte register again will automatically refresh this stored low byte data.

## 6.2 Temperature Data Registers

As shown in the table below, all temperatures are stored as an 11-bit value with the high byte representing the integer value and the low byte representing the fractional value left justified to occupy the MSBits.

**TABLE 6-2: TEMPERATURE DATA REGISTERS**

ADDR	R/W	Register	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
00h	R	Internal Diode High Byte	128	64	32	16	8	4	2	1	00h
29h	R	Internal Diode Low Byte	0.5	0.25	0.125	—	—	—	—	—	00h
01h	R	External Diode High Byte	128	64	32	16	8	4	2	1	00h
10h	R	External Diode Low Byte	0.5	0.25	0.125	—	—	—	—	—	00h

## 6.3 Status Register

Name	Bits	Address	Type	Default
Status	8	02h	RC	00h

The Status Register reports the operating status of the Internal Diode and External Diode channels. When any of the bits are set (excluding the BUSY bit) either the  $\overline{\text{ALERT}}$  or  $\overline{\text{THERM}}$  pin is being asserted.

The  $\overline{\text{ALERT}}$  and  $\overline{\text{THERM}}$  pins are controlled by the respective consecutive alert counters (see [Section 6.11 “Consecutive ALERT Register”](#)) and will not be asserted until the programmed consecutive alert count has been reached. The status bits (except  $\overline{\text{E1THERM}}$  and  $\overline{\text{ITHERM}}$ ) will remain set until read unless the  $\overline{\text{ALERT}}$  pin is configured as a second  $\overline{\text{THERM}}$  output (see [Section 4.3.2 “ALERT Pin Comparator Mode”](#)).

### REGISTER 6-1: STATUS REGISTER (ADDRESS 02H)

RC-0	RC-0	RC-0	RC-0	RC-0	RC-0	RC-0	RC-0
BUSY	IHIGH	ILOW	EHIGH	ELOW	FAULT	ETHERM	ITHERM
bit 7							bit 0

#### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared
RC = Read-then-clear bit	x = Bit is unknown	

- bit 7 **BUSY:** This bit indicates that the ADC is currently converting. This bit does not cause either the  $\overline{\text{ALERT}}$  or  $\overline{\text{THERM}}$  pins to be asserted.
- bit 6 **IHIGH:** This bit is set when the Internal Diode channel exceeds its programmed high limit. When set, this bit will assert the  $\overline{\text{ALERT}}$  pin.
- bit 5 **ILOW:** This bit is set when the Internal Diode channel drops below its programmed low limit. When set, this bit will assert the  $\overline{\text{ALERT}}$  pin.
- bit 4 **EHIGH:** This bit is set when the External Diode channel exceeds its programmed high limit. When set, this bit will assert the  $\overline{\text{ALERT}}$  pin.
- bit 3 **ELOW:** This bit is set when the External Diode channel drops below its programmed low limit. When set, this bit will assert the  $\overline{\text{ALERT}}$  pin.
- bit 2 **FAULT:** This bit is asserted when a diode fault is detected. When set, this bit will assert the  $\overline{\text{ALERT}}$  pin.
- bit 1 **ETHERM:** This bit is set when the External Diode channel exceeds the programmed Therm Limit. When set, this bit will assert the  $\overline{\text{THERM}}$  pin. This bit will remain set until the  $\overline{\text{THERM}}$  pin is released at which point it will be automatically cleared.
- bit 0 **ITHERM:** This bit is set when the Internal Diode channel exceeds the programmed Therm Limit. When set, this bit will assert the  $\overline{\text{THERM}}$  pin. This bit will remain set until the  $\overline{\text{THERM}}$  pin is released at which point it will be automatically cleared.

# EMC1412

## 6.4 Configuration Register

Name	Bits	Address	Type	Default
Configuration	8	03h	R/W	00h
		09h		

The Configuration Register controls the basic operation of the device. This register is fully accessible at addresses 03h and 09h.

### REGISTER 6-2: CONFIGURATION REGISTER (ADDRESSES 03H AND 09H)

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	U-0
MASK_ALL	RUN/STOP	ALERT/COMP	RECD	—	RANGE	DAVG_DIS	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 7 **MASK\_ALL:** Masks the  $\overline{\text{ALERT}}$  from asserting.
- 1 = The  $\overline{\text{ALERT}}$  pin is not masked. If any of the appropriate status bits are set the  $\overline{\text{ALERT}}$  pin will be asserted.
  - 0 = The  $\overline{\text{ALERT}}$  pin is masked. It will not be asserted for any interrupt condition unless it is configured in comparator mode. The Status Register will be updated normally. This is the default setting.
- bit 6 **RUN/STOP:** Controls Active/Standby modes.
- 1 = The device is in Standby mode and not converting.
  - 0 = The device is in Active mode and converting on all channels. This is the default setting.
- bit 5 **ALERT/COMP:** Controls the operation of the  $\overline{\text{ALERT}}$  pin.
- 1 = The  $\overline{\text{ALERT}}$  pin acts in comparator mode as described in [Section 4.3.2 “ALERT Pin Comparator Mode”](#). In this mode the MASK\_ALL bit is ignored.
  - 0 = The  $\overline{\text{ALERT}}$  pin acts as described in [Section 4.3 “ALERT Output”](#). This is the default setting.
- bit 4 **RECD1:** Disables the Resistance Error Correction (REC) for External Diode 1.
- 1 = REC is disabled for External Diode 1.
  - 0 = REC is enabled for External Diode 1. This is the default setting.
- bit 3 **Unimplemented:** read as '0'
- bit 2 **RANGE:** Configures the measurement range and data format of the temperature channels.
- 1 = The temperature measurement range is -64°C to +191.875°C and the data format is offset binary (see [Table 4-2](#)).
  - 0 = The temperature measurement range is 0°C to +127.875°C and the data format is binary. This is the default setting.
- bit 1 **DAVG\_DIS:** Disables the dynamic averaging feature on all temperature channels.
- 1 = The dynamic averaging feature is disabled. All temperature channels will be converted with a maximum averaging factor of 1x (equivalent to 11-bit conversion). For higher conversion rates, this averaging factor will be reduced as shown in [Table 4-1](#).
  - 0 = The dynamic averaging feature is enabled. All temperature channels will be converted with an averaging factor that is based on the conversion rate as shown in [Table 4-1](#). This is the default setting.
- bit 0 **Unimplemented:** read as '0'



## 6.5 Conversion Rate Register

Name	Bits	Address	Type	Default
Conversion Rate	8	04h	R/W	06h (4/sec)
		04Ah		

The Conversion Rate Register controls how often the temperature measurement channels are updated and compared against the limits. This register is fully accessible at either address.

### REGISTER 6-3: CONVERSION RATE REGISTER (ADDRESSES 04H AND 0AH)

U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	—	—	CONV[3:0]			
bit 7				bit 0			

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 **Unimplemented:** read as '0'.

bit 3-0 **CONV[3:0]:** Determines the conversion rate.

0000 = 1/16 conversions per second

0001 = 1/8 conversions per second

0010 = 1/4 conversions per second

0011 = 1/2 conversions per second

0100 = one conversion per second

0101 = two conversions per second

0110 = four conversions per second (default)

0111 = eight conversions per second

1000 = 16 conversions per second

1001 = 32 conversions per second

1010 = 64 conversions per second

All other configurations set the device to one conversion per second.

## 6.6 Limit Registers

The device contains both high and low limits for all temperature channels. If the measured temperature exceeds the high limit, then the corresponding status bit is set and the ALERT pin is asserted. Likewise, if the measured temperature is less than or equal to the low limit, the corresponding status bit is set and the ALERT pin is asserted.

The data format for the limits must match the selected data format for the temperature so that if the extended temperature range is used, the limits must be programmed in the extended data format.

The limit registers with multiple addresses are fully accessible at either address.

When the device is in Standby mode, updating the limit registers will have no effect until the next conversion cycle occurs. This can be initiated via a write to the

One-Shot Register or by clearing the RUN/STOP bit in the Configuration Register (see [Section 6.4 "Configuration Register"](#)).

# EMC1412

**TABLE 6-3: TEMPERATURE LIMIT REGISTERS**

Addr.	R/W	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
05h	R/W	Internal Diode High Limit	128	64	32	16	8	4	2	1	55h (+85°C)
0Bh											
06h	R/W	Internal Diode Low Limit	128	64	32	16	8	4	2	1	00h (0°C)
0Ch											
07h	R/W	External Diode High Limit High Byte	128	64	32	16	8	4	2	1	55h (+85°C)
0Dh											
13h	R/W	External Diode High Limit Low Byte	0.5	0.25	0.125	—	—	—	—	—	00h
08h	R/W	External Diode Low Limit High Byte	128	64	32	16	8	4	2	1	00h (0°C)
0Eh											
14h	R/W	External Diode Low Limit Low Byte	0.5	0.25	0.125	—	—	—	—	—	00h

## 6.7 Scratchpad Registers

The Scratchpad Registers are Read/Write registers that are used for place holders to be software compatible with legacy programs. Reading from the registers will return what is written to them.

**TABLE 6-4: SCRATCHPAD REGISTERS**

Addr.	R/W	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
11h	R/W	Scratchpad	7	6	5	4	3	2	1	0	00h
12h	R/W	Scratchpad	7	6	5	4	3	2	1	0	00h

## 6.8 One-Shot Register

The One-Shot Register is used to initiate a one-shot command. Writing to the one-shot register when the device is in Standby mode and the BUSY bit in the Status Register is '0' will immediately cause the ADC to update all temperature measurements. Writing to the One-Shot Register while the device is in Active mode will have no effect.

**REGISTER 6-4: ONE-SHOT REGISTER (ADDRESS 0FH)**

W-0	W-0	W-0	W-0	W-0	W-0	W-0	W-0
ONE_SHOT[7:0]							
bit 7							bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

bit 7-0      **ONE\_SHOT[7:0]:** Writing to this register initiates a single conversion cycle. Data is not stored and always reads 00h.

## 6.9 Therm Limit Registers

The Therm Limit Registers are used to determine whether a critical thermal event has occurred. If the measured temperature exceeds the Therm Limit, the THERM pin is asserted. The limit setting must match the chosen data format of the temperature reading registers.

Unlike the ALERT pin, the THERM pin cannot be masked. Additionally, the THERM pin will be released once the temperature drops below the corresponding threshold minus the Therm Hysteresis.

**TABLE 6-5: THERM LIMIT REGISTERS**

Addr.	R/W	Register Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default
19h	R/W	External Diode Therm Limit	128	64	32	16	8	4	2	1	55h (+85°C)
20h	R/W	Internal Diode Therm Limit	128	64	32	16	8	4	2	1	55h (+85°C)
21h	R/W	Therm Hysteresis	128	64	32	16	8	4	2	1	0Ah (10°C)

## 6.10 Channel Mask Register

The Channel Mask Register controls individual channel masking. When a channel is masked, the ALERT pin will not be asserted when the masked channel reads a diode fault or out-of-limit error. The channel mask does not mask the THERM pin.

**REGISTER 6-5: CHANNEL MASK REGISTER (ADDRESS 1FH)**

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	EMASK	INTMASK
bit 7						bit 0	

**Legend:**

# EMC1412

## REGISTER 6-5: CHANNEL MASK REGISTER (ADDRESS 1FH) (CONTINUED)

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

- bit 7-2      Unimplemented bits always read as '0'.
- bit 1      **EMASK:** Masks the  $\overline{\text{ALERT}}$  pin from asserting when the External Diode channel is out-of-limit or reports a diode fault.
- 1 = The External Diode channel will not cause the  $\overline{\text{ALERT}}$  pin to be asserted if it is out-of-limit or reports a diode fault.
  - 0 = The External Diode channel will cause the  $\overline{\text{ALERT}}$  pin to be asserted if it is out-of-limit or reports a diode fault. This is the default setting.
- bit 0      **INTMASK:** Masks the  $\overline{\text{ALERT}}$  pin from asserting when the Internal Diode temperature is out-of-limit.
- 1 = The Internal Diode channel will not cause the  $\overline{\text{ALERT}}$  pin to be asserted if it is out-of-limit.
  - 0 = The Internal Diode channel will cause the  $\overline{\text{ALERT}}$  pin to be asserted if it is out-of-limit. This is the default setting.

### 6.11 Consecutive $\overline{\text{ALERT}}$ Register

Name	Bits	Address	Type	Default
Consecutive $\overline{\text{ALERT}}$	8	22h	R/W	70h

The Consecutive  $\overline{\text{ALERT}}$  register determines how many times an out-of-limit error or diode fault must be detected in consecutive measurements before the  $\overline{\text{ALERT}}$  or  $\overline{\text{THERM}}$  pin is asserted. Additionally, the Consecutive  $\overline{\text{ALERT}}$  register controls the SMBus Timeout functionality.

An out-of-limit condition (i.e. HIGH, LOW, or FAULT) occurring on the same temperature channel in consecutive measurements will increment the consecutive alert counter. The counters will also be reset if no out-of-limit condition or diode fault condition occurs in a consecutive reading.

When the  $\overline{\text{ALERT}}$  pin is configured as an interrupt and when the consecutive alert counter reaches its programmed value, the following will occur: the STATUS bit(s) for that channel and the last error condition(s) (i.e. EHIGH) will be set to '1', the  $\overline{\text{ALERT}}$  pin will be asserted, the consecutive alert counter will be cleared and measurements will continue. When the  $\overline{\text{ALERT}}$  pin is configured as a comparator, the consecutive alert counter will ignore diode fault and low limit errors and only increment if the measured temperature exceeds the High Limit. Additionally, once the consecutive alert counter reaches the programmed limit, the  $\overline{\text{ALERT}}$  pin will be asserted, but the counter will not be reset. It will remain set until the temperature drops below the High Limit minus the Therm Hysteresis value.

For example, if the CALRT<2:0> bits are set for 4 consecutive alerts on an EMC1412 device, the high limits are set at +70°C and none of the channels are masked, then the  $\overline{\text{ALERT}}$  pin will be asserted after the following five measurements:

- Internal Diode reads +71°C and the external

diode reads +69°C. Consecutive alert counter for INT is incremented to 1.

- Both the Internal Diode and the External Diode read +71°C. Consecutive alert counter for INT is incremented to 2 and for EXT is set to 1.
- The External Diode reads +71°C and the Internal Diode reads +69°C. Consecutive alert counter for INT is cleared and EXT is incremented to 2.
- The Internal Diode reads +71°C and the external diode reads +71°C. Consecutive alert counter for INT is set to 1 and EXT is incremented to 3.
- The Internal Diode reads +71°C and the external diode reads +71°C. Consecutive alert counter for INT is incremented to 2 and EXT is incremented to 4. The appropriate status bits are set for EXT and the  $\overline{\text{ALERT}}$  pin is asserted. EXT counter is reset to 0 and all other counters hold the last value until the next temperature measurement.

## REGISTER 6-6: CONSECUTIVE ALERT REGISTER (ADDRESS 22H)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
TIMEOUT	CTHRM[6:4]			CALRT[3:1]			—
bit 7							bit 0

### Legend:

R = Readable bit  
-n = Value at POR

W = Writable bit  
'1' = Bit is set

U = Unimplemented bit, read as '0'  
'0' = Bit is cleared  
x = Bit is unknown

- bit 7      **TIMEOUT:** Determines whether the SMBus Timeout function is enabled.  
 1 = The SMBus Timeout feature is enabled. If the SMCLK line is held low for more than 30 ms, the device will reset the SMBus protocol.  
 0 = The SMBus Timeout feature is disabled. The SMCLK line can be held low indefinitely without the device resetting its SMBus protocol. This is the default setting.
- bit 6-4      **CTHRM[6:4]:** Determines the number of consecutive measurements that must exceed the corresponding Therm Limit before the THERM pin is asserted. All temperature channels use this value to set the respective counters. The consecutive Therm counter is incremented whenever any measurement exceed the corresponding Therm Limit.  
 If the temperature drops below the Therm Limit, the counter is reset. If a number of consecutive measurements above the Therm Limit occur, the THERM pin is asserted low.  
 Once the THERM pin has been asserted, the consecutive therm counter will not reset until the corresponding temperature drops below the Therm Limit minus the Therm Hysteresis value.  
 000 = The THERM pin will be asserted after one out-of-limit measurement.  
 001 = The THERM pin will be asserted after two consecutive out-of-limit measurements.  
 011 = The THERM pin will be asserted after three consecutive out-of-limit measurements.  
 111 = The THERM pin will be asserted after four consecutive out-of-limit measurements. This is the default setting.
- bit 3-1      **CALRT[3:1]:** Determines the number of consecutive measurements that must have an out-of-limit condition or diode fault before the ALERT pin is asserted. All temperature channels use this value to set the respective counters.  
 000 = The ALERT pin will be asserted after one out-of-limit measurement or diode fault. This is the default setting.  
 001 = The ALERT pin will be asserted after two consecutive out-of-limit measurements or diode faults.  
 011 = The ALERT pin will be asserted after three consecutive out-of-limit measurements or diode faults.  
 111 = The ALERT pin will be asserted after four consecutive out-of-limit measurements or diode faults.
- bit 0      Unimplemented bits always read as '0'.

# EMC1412

## 6.12 Beta Configuration Register

This register is used to set the Beta Compensation factor that is used for the external diode channel.

Name	Bits	Address	Type	Default
Beta Configuration	8	25h	R/W	08h

### REGISTER 6-7: BETA CONFIGURATION REGISTER (ADDRESS 25H)

U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0	R/W-0
—	—	—	—	ENABLE	BETA[2:0]		
bit 7				bit 0			

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-4 Unimplemented bits always read as '0'.

bit 3 **ENABLE1:** Enables or disables the Beta Compensation factor auto-detection function.

1 = The Beta Compensation factor auto-detection circuitry is enabled. At the beginning of every conversion, the optimal Beta Compensation factor setting will be determined and applied. The BETA1[2:0] bits will be automatically updated to indicate the current setting.

0 = The Beta Compensation Factor auto-detection circuitry is disabled.

bit 2-0 **BETA[2:0]:** These bits always reflect the current beta configuration settings. If auto-detection circuitry is enabled, these bits will be updated automatically and writing to these bits will have no effect. If the auto-detection circuitry is disabled, these bits will determine the beta configuration setting that is used for their respective channels ([Note 1](#)).

000 = Indicates a minimum beta compensation factor of 0.11. This is the default configuration.

001 = Indicates a minimum beta compensation factor of 0.18

010 = Indicates a minimum beta compensation factor of 0.25

011 = Indicates a minimum beta compensation factor of 0.33

100 = Indicates a minimum beta compensation factor of 0.43

101 = Indicates a minimum beta compensation factor of 1.00

110 = Indicates a minimum beta compensation factor of 2.33

111 = Disabled

**Note 1:** Care should be taken when setting the BETA[2:0] bits when the auto-detection circuitry is disabled. If the Beta Compensation factor is set at a beta value that is higher than the transistor beta, the circuit may introduce measurement errors. When measuring a discrete thermal diode (such as 2N3904) or a CPU diode that functions like a discrete thermal diode (such as an AMD processor diode), the BETA[2:0] bits should be set to '111b'.

## 6.13 External Diode Ideality Factor Register

This register stores the ideality factors that are applied to the external diodes. [Table 6-6](#) defines each setting and the corresponding ideality factor. Beta Compensation and Resistance Error Correction automatically correct for most diode ideality errors; therefore, it is not recommended that these settings be updated without consulting Microchip.

**REGISTER 6-8: EXTERNAL DIODE IDEALITY FACTOR REGISTER (ADDRESS 27H)**

U-0	U-0	R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0	
—	—	IDEALITY[5:0]						
bit 7								bit 0

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared      x = Bit is unknown

bit 7-6      Unimplemented bits always read as '0'.

bit 5-0      **IDEALITY[5:0]:** These bits set the ideality factor for the External Diode channel.

[Table 6-6](#) shows the ideality factor configuration using the diode model for temperature measurement.

[Table 6-7](#) shows the ideality factor configuration under the BJT transistor model.

**TABLE 6-6: IDEALITY FACTOR LOOK-UP TABLE (DIODE MODEL)**

Setting	Factor	Setting	Factor	Setting	Factor
08h	0.9949	18h	1.0159	28h	1.0371
09h	0.9962	19h	1.0172	29h	1.0384
0Ah	0.9975	1Ah	1.0185	2Ah	1.0397
0Bh	0.9988	1Bh	1.0200	2Bh	1.0410
0Ch	1.0001	1Ch	1.0212	2Ch	1.0423
0Dh	1.0014	1Dh	1.0226	2Dh	1.0436
0Eh	1.0027	1Eh	1.0239	2Eh	1.0449
0Fh	1.0040	1Fh	1.0253	2Fh	1.0462
10h	1.0053	20h	1.0267	30h	1.0475
11h	1.0066	21h	1.0280	31h	1.0488
12h (default)	1.0080	22h	1.0293	32h	1.0501
13h	1.0093	23h	1.0306	33h	1.0514
14h	1.0106	24h	1.0319	34h	1.0527
15h	1.0119	25h	1.0332	35h	1.0540
16h	1.0133	26h	1.0345	36h	1.0553
17h	1.0146	27h	1.0358	37h	1.0566

# EMC1412

For CPU substrate transistors that require the BJT transistor model, the ideality factor behaves slightly differently than for discrete diode-connected transistors. Refer to the table below when using a CPU substrate transistor.

**TABLE 6-7: SUBSTRATE DIODE IDEALITY FACTOR LOOK-UP TABLE (BJT MODEL)**

Setting	Factor	Setting	Factor	Setting	Factor
08h	0.9869	18h	1.0079	28h	1.0291
09h	0.9882	19h	1.0092	29h	1.0304
0Ah	0.9895	1Ah	1.0105	2Ah	1.0317
0Bh	0.9908	1Bh	1.0120	2Bh	1.0330
0Ch	0.9921	1Ch	1.0132	2Ch	1.0343
0Dh	0.9934	1Dh	1.0146	2Dh	1.0356
0Eh	0.9947	1Eh	1.0159	2Eh	1.0369
0Fh	0.9960	1Fh	1.0173	2Fh	1.0382
10h	0.9973	20h	1.0187	30h	1.0395
11h	0.9986	21h	1.0200	31h	1.0408
12h (default)	1.0000	22h	1.0213	32h	1.0421
13h	1.0013	23h	1.0226	33h	1.0434
14h	1.0026	24h	1.0239	34h	1.0447
15h	1.0039	25h	1.0252	35h	1.0460
16h	1.0053	26h	1.0265	36h	1.0473
17h	1.0066	27h	1.0278	37h	1.0486

**Note 1:** When measuring a 65 nm Intel CPU, the Ideality Setting should be the default 12h. When measuring a 45 nm Intel CPU, the Ideality Setting should be 15h.

## 6.14 Filter Control Register

The Filter Configuration Register controls the digital filter on the External Diode channel.

Name	Bits	Address	Type	Default
Filter Configuration	8	40h	R/W	00h

**REGISTER 6-9: FILTER CONTROL REGISTER (ADDRESS 40H)**

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	FILTER[1:0]	
bit 7						bit 0	

**Legend:**

R = Readable bit                      W = Writable bit                      U = Unimplemented bit, read as '0'  
 -n = Value at POR                      '1' = Bit is set                      '0' = Bit is cleared                      x = Bit is unknown

bit 7-2                      Unimplemented bits always read as '0'.

bit 1-0                      **FILTER[1:0]:** Controls the level of digital filtering that is applied to the External Diode temperature measurement. See [Figure 4-2](#) and [Figure 4-3](#) for examples on the filter behavior.

- 00 = Averaging is disabled
- 01 = Level 1 Averaging is enabled
- 10 = Level 1 Averaging is enabled
- 11 = Level 2 Averaging is enabled



## 6.15 Product ID Register

The Product ID Register holds a unique value that identifies the device.

**TABLE 6-8: PRODUCT ID REGISTER**

Register Address	Register Name	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit2	Bit0	Default
FDh	Product ID	R	0	0	1	0	0	0	0	0	20h

## 6.16 Manufacturer ID Register

The Manufacturer ID register contains an 8-bit word that identifies Microchip as the manufacturer of the EMC1412.

**TABLE 6-9: MANUFACTURER ID REGISTER**

Register Address	Register Name	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit2	Bit0	Default
FEh	MCHP ID	R	0	1	0	1	1	1	0	1	5Dh

## 6.17 Revision Register

The Revision register contains an 8-bit word that identifies the die revision.

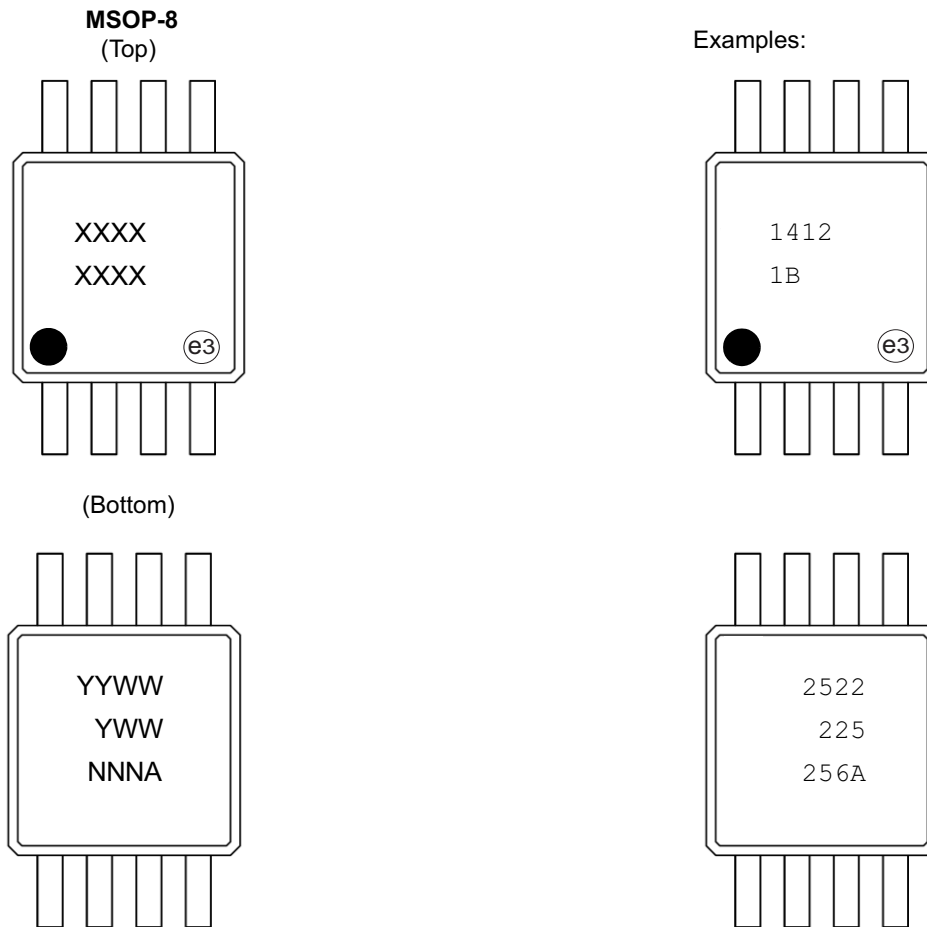
**TABLE 6-10: REVISION REGISTER**

Register Address	Register Name	R/W	Bit7	Bit6	Bit5	Bit4	Bit3	Bit2	Bit2	Bit0	Default
FFh	Revision	R	0	0	0	0	0	1	0	0	04h

# EMC1412

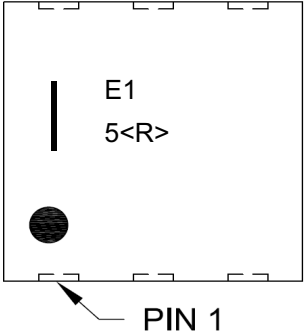
## 7.0 PACKAGING INFORMATION

### 7.1 Package Marking Information

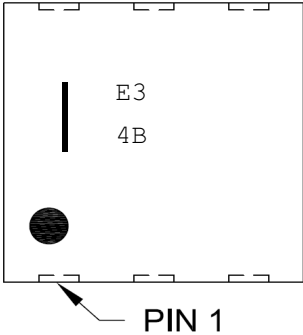
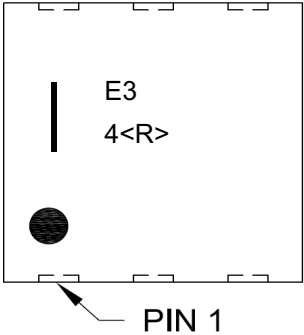
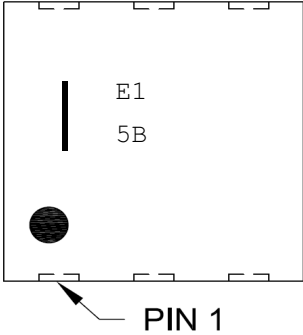


<b>Legend:</b>	XX...X	Device-specific information
	Y	Year code (last digit of calendar year)
	YY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	(e3)	Pb-free JEDEC® designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

TDFN-8



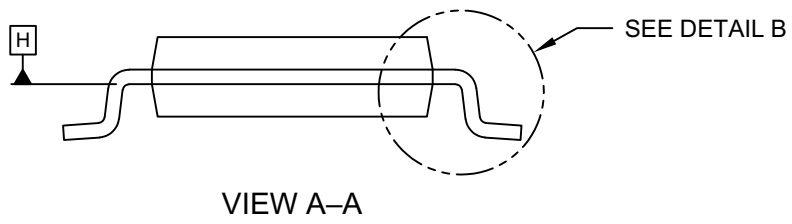
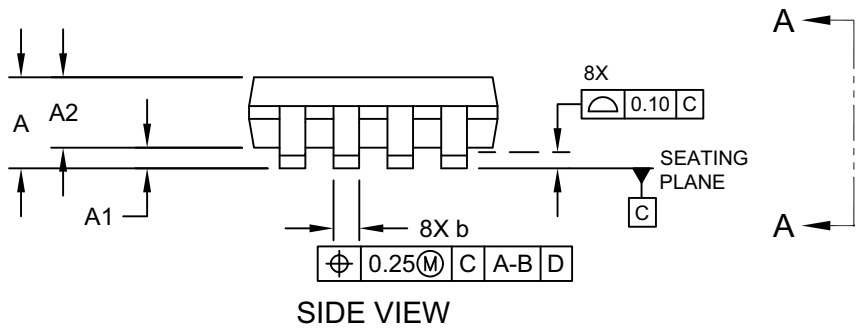
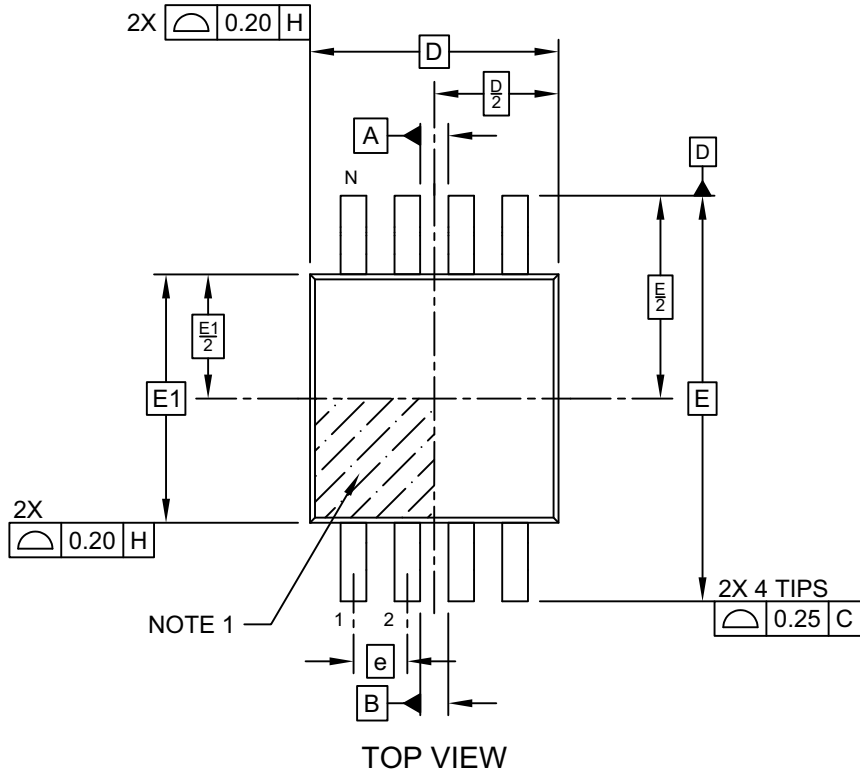
Example:



# EMC1412

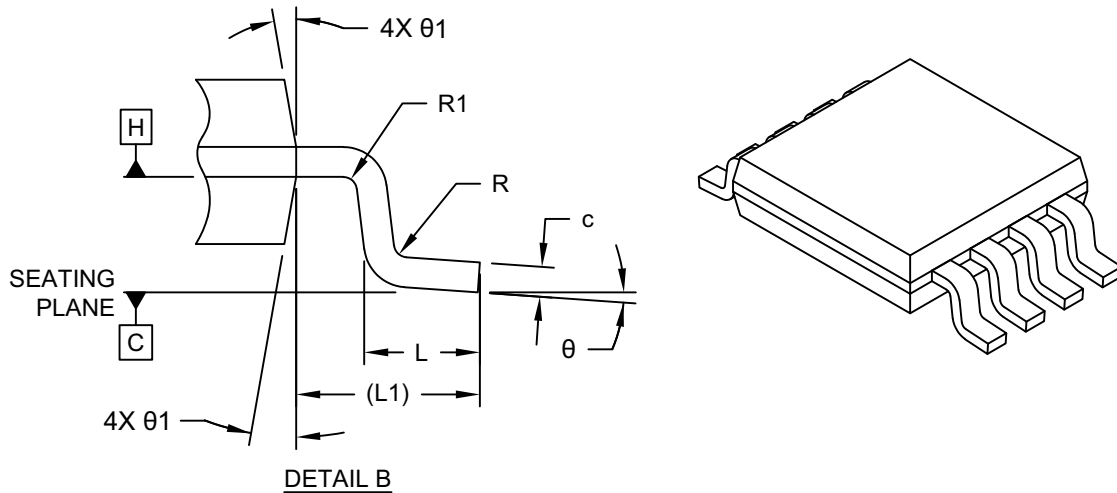
## 8-Lead Plastic Micro Small Outline Package (MS) - 3x3 mm Body [MSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



## 8-Lead Plastic Micro Small Outline Package (MS) - 3x3 mm Body [MSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Number of Terminals	N	8		
Pitch	e	0.65 BSC		
Overall Height	A	–	–	1.10
Standoff	A1	0.00	–	0.15
Molded Package Thickness	A2	0.75	0.85	0.95
Overall Length	D	3.00 BSC		
Overall Width	E	4.90 BSC		
Molded Package Width	E1	3.00 BSC		
Terminal Width	b	0.22	–	0.40
Terminal Thickness	c	0.08	–	0.23
Terminal Length	L	0.40	0.60	0.80
Footprint	L1	0.95 REF		
Lead Bend Radius	R	0.07	–	–
Lead Bend Radius	R1	0.07	–	–
Foot Angle	θ	0°	–	8°
Mold Draft Angle	θ1	5°	–	15°

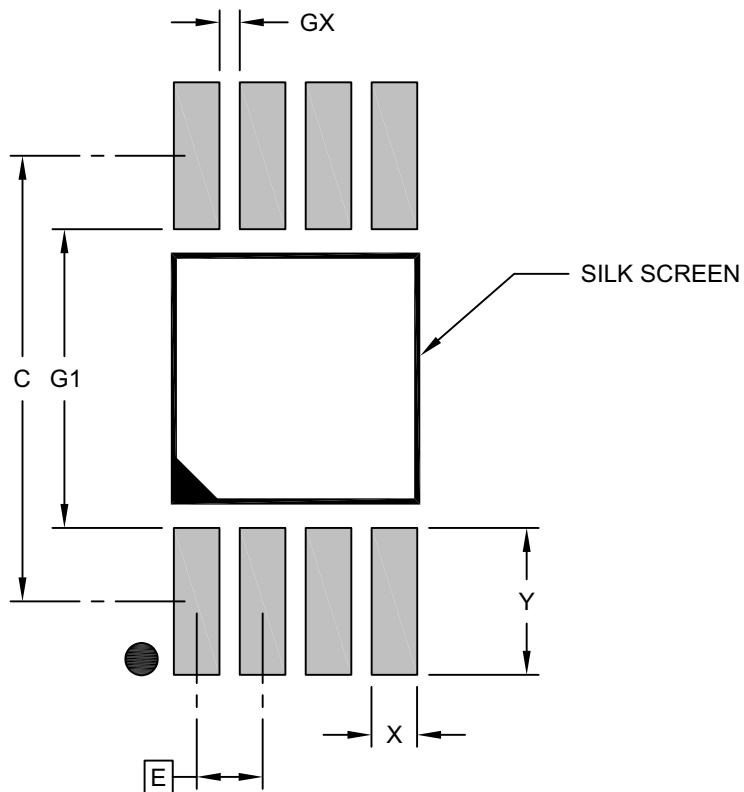
**Notes:**

- Pin 1 visual index feature may vary, but must be located within the hatched area.
- Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side.
- Dimensioning and tolerancing per ASME Y14.5M  
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.  
 REF: Reference Dimension, usually without tolerance, for information purposes only.

# EMC1412

## 8-Lead Plastic Micro Small Outline Package (MS) - 3x3 mm Body [MSOP]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



### RECOMMENDED LAND PATTERN

Dimension Limits	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.65 BSC		
Contact Pad Spacing	C		4.40	
Contact Pad Width (X8)	X			0.45
Contact Pad Length (X8)	Y			1.45
Contact Pad to Contact Pad (X4)	G1	2.95		
Contact Pad to Contact Pad (X6)	GX	0.20		

**Notes:**

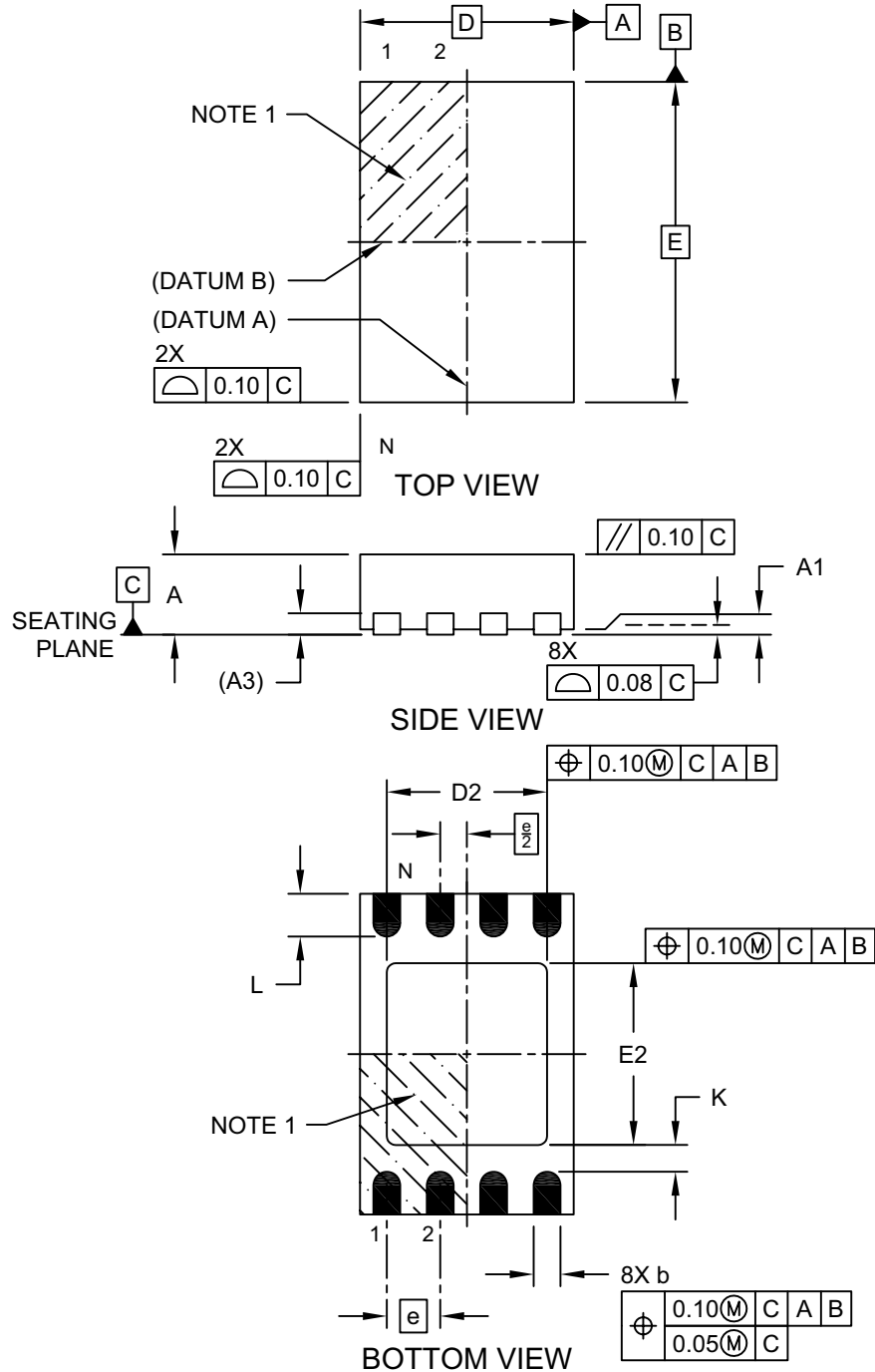
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2111-MS Rev F

## 8-Lead Very Thin Plastic Dual Flat, No Lead Package (8Q) - 2x3 mm Body [VDFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>

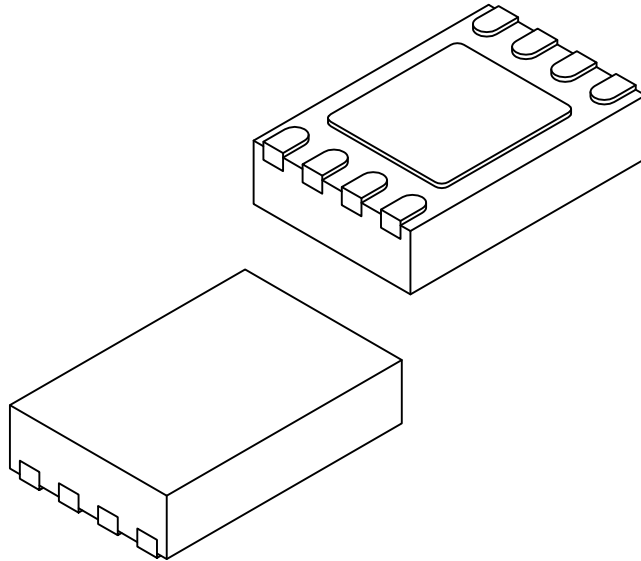


Microchip Technology Drawing C04-382A Sheet 1 of 2

# EMC1412

## 8-Lead Very Thin Plastic Dual Flat, No Lead Package (8Q) - 2x3 mm Body [VDFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



Units		MILLIMETERS		
Dimension Limits		MIN	NOM	MAX
Number of Terminals	N	8		
Pitch	e	0.50 BSC		
Overall Height	A	0.70	0.75	0.80
Standoff	A1	0.00	0.02	0.05
Terminal Thickness	(A3)	0.20 REF		
Overall Length	D	2.00 BSC		
Exposed Pad Length	D2	1.40	1.50	1.60
Overall Width	E	3.00 BSC		
Exposed Pad Width	E2	1.60	1.70	1.80
Terminal Width	b	0.18	0.25	0.30
Terminal Length	L	0.35	0.40	0.45
Terminal-to-Exposed-Pad	K	0.20	-	-

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. Package is saw singulated
3. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

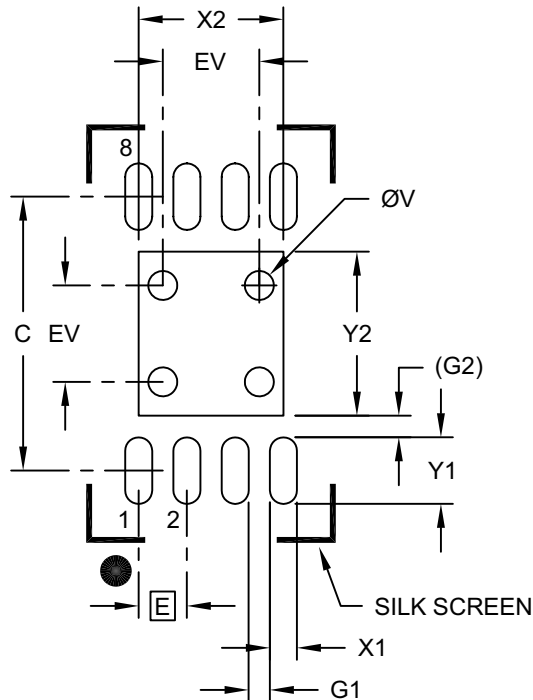
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-382A Sheet 2 of 2



## 8-Lead Very Thin Plastic Dual Flat, No Lead Package (8Q) - 2x3 mm Body [VDFN]

**Note:** For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



### RECOMMENDED LAND PATTERN

Dimension	Units	MILLIMETERS		
		MIN	NOM	MAX
Contact Pitch	E	0.50 BSC		
Optional Center Pad Width	X2			1.50
Optional Center Pad Length	Y2			1.70
Contact Pad Spacing	C	2.84		
Contact Pad Width (X8)	X1			0.28
Contact Pad Length (X8)	Y1			0.69
Space Between Pads	G1	0.20		
Contact Pad to Center Pad (X8)	(G2)	0.225 REF		
Thermal Via Diameter	V		0.30	
Thermal Via Pitch	EV		1.00	

**Notes:**

- Dimensioning and tolerancing per ASME Y14.5M  
BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2382A



## APPENDIX A: REVISION HISTORY

### Revision B (November 2022)

- Document converted to Microchip format
- Updated Package Drawings in [Section 7.1](#) “[Package Marking Information](#)”

### Revision A (February 2015)

- Original release of this document

# EMC1412

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NOTES:

## PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

<u>PART NO.</u>	<u>-X</u>	<u>-XXXX</u>	<u>-XX<sup>(1)</sup></u>	
Device	SMBus Address	Package	Tape and Reel Option	
<b>Device:</b>	EMC1412: Multiple Channel, 1°C Accuracy Temperature Sensors with Beta Compensation			
<b>SMBus Address:</b>	1	= Fixed Address: 1001_100(r/w)		
	A	= Programmable Address		
	2	= Fixed Address: 1001_101(r/w)		
<b>Package:</b>	ACZL	= 8-Lead Plastic Micro Small Outline (MSOP), RoHS Compliant		
	AC3	= 8-Lead Very Thin Plastic Dual Flat, No Lead (TDFN), RoHS Compliant		
<b>Tape and Reel:</b>	TR	= Tape and Reel		
				<b>Examples:</b> a) EMC1412-1-ACZL-TR: 8-pin MSOP package, fixed SMBus Address 1001_100(r/w) b) EMC1412-2-ACZL-TR: 8-pin MSOP package, fixed SMBus Address 1001_101(r/w) c) EMC1412-A-AC3-TR: 8-pin TDFN package, programmable SMBus address selectable via THERM pull-up  <b>Note 1:</b> The Tape and Reel identifier only appears in the catalog part number description. This identifier is used for ordering purposes and is not printed on the device package. Check with your Microchip Sales Office for package availability with the Tape and Reel option.

# EMC1412

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NOTES:

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**Note the following details of the code protection feature on Microchip products:**

- Microchip products meet the specifications contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is secure when used in the intended manner, within operating specifications, and under normal conditions.
- Microchip values and aggressively protects its intellectual property rights. Attempts to breach the code protection features of Microchip product is strictly prohibited and may violate the Digital Millennium Copyright Act.
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