

Product Change Notification / SYST-11ZUV0881

Date:

12-Aug-2022

Product Category:

Interface- Serial Peripherals

PCN Type:

Document Change

Notification Subject:

Data Sheet - MCP23009/MCP23S09 - 8-Bit I/O Expander with Open-Drain Outputs Data Sheet

Affected CPNs:

SYST-11ZUV0881_Affected_CPN_08122022.pdf SYST-11ZUV0881_Affected_CPN_08122022.csv

Notification Text:

SYST-11ZUVO881

Microchip has released a new Datasheet for the MCP23009/MCP23S09 - 8-Bit I/O Expander with Open-Drain Outputs Data Sheet of devices. If you are using one of these devices please read the document located at MCP23009/MCP23S09 - 8-Bit I/O Expander with Open-Drain Outputs Data Sheet.

Notification Status: Final

Description of Change:

Added information about the Automotive Qualification status of the device in Section "Features". Clarified Section 3.1 "Package Marking Information" to more closely match manufacturing standards. Updated Section "Product Identification System", with Automotive Qualified devices. Minor text and format changes throughout.

Impacts to Data Sheet: None

Change Implementation Status: Complete

Date Document Changes Effective: 12 Aug 2022

NOTE: Please be advised that this is a change to the document only the product has not been changed.

Markings to Distinguish Revised from Unrevised Devices::N/A
Attachments:
MCP23009/MCP23S09 - 8-Bit I/O Expander with Open-Drain Outputs Data Sheet
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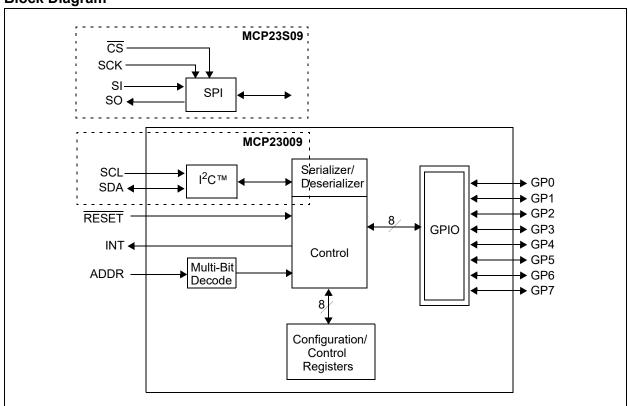
8-Bit I/O Expander with Open-Drain Outputs

Features

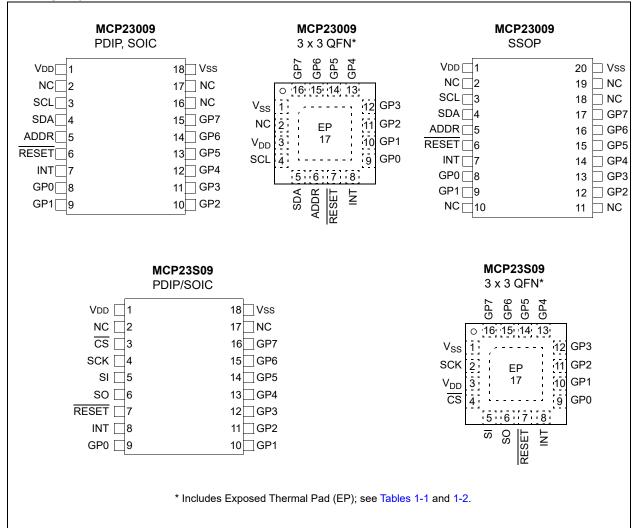
- · AEC-Q100 Qualified
- 8-Bit Remote Bidirectional I/O Port:
 - I/O Pins Default to Input
- · Open-Drain Outputs:
 - 5.5V Tolerant
 - 25 mA Sink Capable (per Pin)
 - 200 mA Total
- High-Speed I²C™ Interface (**MCP23009**):
 - 100 kHz
 - 400 kHz
 - 3.4 MHz
- · High-Speed SPI Interface (MCP23S09):
 - 10 MHz
- Single Hardware Address Pin (MCP23009):
 - Voltage input to allow up to eight devices on the bus
- · Configurable Interrupt Output Pins:

- Configurable as active-high, active-low or open-drain
- · Configurable Interrupt Source:
 - Interrupt-on-Change from configured defaults or pin change
- Polarity inversion register to configure the polarity of the input port data
- · External Reset Input
- · Low Standby Current:
 - $1 \mu A (-40^{\circ}C \le TA \le +85^{\circ}C)$
 - $6 \mu A (+85^{\circ}C \le TA \le +125^{\circ}C)$
- · Operating Voltage:
 - 1.8V to 5.5V
- · Available Packages:
 - 16-Lead QFN (3x3x0.9 mm)
 - 18-Lead PDIP (300 mil)
 - 18-Lead SOIC (7.50 mm)
 - 20-Lead SSOP (5.30 mm)

Block Diagram



Package Types



1.0 DEVICE OVERVIEW

MCP23X09 device provides 8-bit, general purpose parallel I/O expansion for I²C bus or SPI applications. The two devices differ only in the serial interface.

- MCP23009 I²C interface
- MCP23S09 SPI interface

MCP23X09 consists of multiple 8-bit configuration registers for input, output and polarity selection. The system host can enable the I/Os as either inputs or outputs by writing the I/O configuration bits. The data for each input or output is kept in the corresponding input or output register. The polarity of the input port register can be inverted with the polarity inversion register. All registers can be read by the system host.

The interrupt output can be configured to activate under two conditions (mutually exclusive):

- When any input state differs from its corresponding input port register state. This is used to indicate to the system host that an input state has changed.
- 2. When an input state differs from a preconfigured register value (DEFVAL register).

The Interrupt Capture register captures port values at the time of the Interrupt, thereby saving the condition that caused the Interrupt.

The Power-On Reset (POR) sets the registers to their default values and initializes the device state machine.

The hardware address pin is used to determine the device address.

1.1 Pin Descriptions

TABLE 1-1: I²C™ PINOUT DESCRIPTION (MCP23009)

D .		Pin Numbe	er	D:	
Pin Name	16-lead QFN	18-lead PDIP/SOIC	20-lead SSOP	Pin Type	Standard Function
VDD	3	1	1	Р	Power
NC	2	2, 16-17	2, 10-11, 18-19	_	Not connected
SCL	4	3	3	I	Serial clock input
SDA	5	4	4	I/O	Serial data I/O
ADDR	6	5	5	I	Hardware address pin allows up to eight client devices on the bus
RESET	7	6	6	- 1	Hardware reset
INT	8	7	7	0	Interrupt output for port. Can be configured as active-high, active-low or open-drain.
GP0	9	8	8	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP1	10	9	9	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP2	11	10	12	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP3	12	11	13	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP4	13	12	14	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP5	14	13	15	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP6	15	14	16	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
GP7	16	15	17	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for interrupt on change and/or internal pull-up resistor.
Vss	1	18	20	Р	Ground
EP	17	_	_	_	Exposed Thermal Pad (EP). Can be left floating or connected to Vss.

TABLE 1-2: SPI PINOUT DESCRIPTION (MCP23S09)

Di-	Pin	Number	D:					
Pin Name	16-lead QFN	18-lead PDIP/SOIC	Pin Type	Standard Function				
VDD	3	1	Р	Power (high-current capable)				
NC	_	2, 17	_	Not connected				
CS	4	3	1	Chip select				
SCK	2	4	1	Serial clock input				
SI	5	5	I	Serial data input				
SO	6	6	0	Serial data out				
RESET	7	7	I	Hardware reset (must be externally biased)				
INT	8	8	0	Interrupt output for port. Can be configured as active-high, active-low or open-drain.				
GP0	9	9	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP1	10	10	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP2	11	11	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP3	12	12	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP4	13	13	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP5	14	14	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP6	15	15	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
GP7	16	16	I/O	Bidirectional I/O pin (5.5V tolerant inputs; open-drain outputs). Can be enabled for Interrupt-on-Change and/or internal pull-up resistor.				
Vss	1	18	Р	Ground (high-current capable)				
EP	17	_	_	Exposed Thermal Pad (EP). Can be left floating or connected to Vss.				

1.2 Power-On Reset (POR)

The on-chip POR circuit holds the device in reset until VDD has reached a high enough voltage to deactivate the POR circuit (i.e., release the device from reset). The maximum VDD rise time is specified in the electrical specification section.

When the device exits the POR condition (releases reset), the device operating parameters (i.e., voltage, temperature, serial bus frequency, etc.) must be met to ensure proper operation.

1.3 Serial Interface

This block handles the functionality of the I^2C (MCP23009) or SPI (MCP23S09) interface protocol. MCP23X09 contains eleven (11) individual registers which can be addressed through the Serial Interface block (Table 1-3).

TABLE 1-3: REGISTER ADDRESSES

Address	Access to
00h	IODIR
01h	IPOL
02h	GPINTEN
03h	DEFVAL
04h	INTCON
05h	IOCON
06h	GPPU
07h	INTF
08h	INTCAP (read-only)
09h	GPIO
0Ah	OLAT

1.3.1 BYTE MODE AND SEQUENTIAL MODE

MCP23X09 has the ability to operate in Byte mode or Sequential mode (IOCON.SEQOP). Byte mode and Sequential mode are not to be confused with I²C byte operations and sequential operations. The modes explained here relate to the device's internal address pointer and whether or not it is incremented after each byte is clocked on the serial interface.

 Byte mode disables automatic address pointer incrementing. When operating in Byte mode, MCP23X09 does not increment its internal address counter after each byte during the data transfer. This gives the ability to continually access the same address by providing extra clocks (without additional control bytes). This is useful for polling the GPIO register for data changes or for continually writing to the output latches. Sequential mode enables automatic address pointer incrementing. When operating in Sequential mode, MCP23X09 increments its address counter after each byte during the data transfer. The address pointer automatically rolls over to address 00h after accessing the last register.

These two modes are not to be confused with single writes/reads and continuous writes/reads, which are serial protocol sequences. For example, the device may be configured for Byte mode and the host may perform a continuous read. In this case, MCP23X09 would not increment the address pointer and would repeatedly drive data from the same location.

1.3.2 I²C INTERFACE

1.3.2.1 I²C Write Operation

The I²C write operation includes the control byte and the register address sequence, as shown in the bottom of Figure 1-1. This sequence is followed by eight bits of data from the host and an Acknowledge (ACK) from MCP23009. The operation is ended with a Stop (P) or Restart (SR) condition being generated by the host.

Data is written to MCP23009 after every byte transfer. If a Stop or Restart condition is generated during a data transfer, the data will not be written to MCP23009.

Both Byte mode and Sequential mode are supported by MCP23009. If Sequential mode is enabled (default), MCP23009 increments its address counter after each ACK during the data transfer.

1.3.2.2 I²C Read Operation

 I^2C read operations include the control byte sequence, as shown in the bottom of Figure 1-1. This sequence is followed by another control byte (including the Start condition and ACK) with the R/W bit equal to a logic one (R/W = 1). MCP23009 then transmits the data contained in the addressed register. The sequence is ended with the host generating a Stop or Restart condition.

1.3.2.3 I²C Sequential Write/Read

For sequential operations (Write or Read), instead of transmitting a Stop or Restart condition after the data transfer, the host clocks the next byte pointed to by the address pointer (see **Section 1.3.1 "Byte Mode and Sequential Mode"** for details regarding sequential operation control).

The sequence ends with the host sending a Stop or Restart condition.

MCP23009 address pointer will roll over to address zero after reaching the last register address.

Refer to Figure 1-1.

1.3.3 SPI INTERFACE

MCP23S09 operates in Mode 0,0 and Mode 1,1. The difference between the two modes is the idle state of the clock.

- Mode 0,0: The idle state of the clock is low. Input data is latched on the rising edge of the clock; output data is driven on the falling edge of the clock.
- Mode 1,1: The idle state of the clock is high. Input data is latched on the rising edge of the clock; output data is driven on the falling edge of the clock.

1.3.3.1 SPI Write Operation

The SPI write operation is started by lowering \overline{CS} . The write command (client address with R/W bit cleared) is then clocked into the device. The opcode is followed by an address and at least one data byte.

1.3.3.2 SPI Read Operation

The SPI read operation is started by lowering \overline{CS} . The SPI read command (client address with R/W bit set) is then clocked into the device. The opcode is followed by an address, with at least one data byte being clocked out of the device.

1.3.3.3 SPI Sequential Write/Read

For sequential operations, instead of deselecting the device by raising \overline{CS} , the host clocks the next byte pointed to by the address pointer (see Section 1.3.1 "Byte Mode and Sequential Mode" for details regarding sequential operation control).

The sequence ends by the raising of $\overline{\text{CS}}$.

MCP23S09 address pointer will roll over to address zero after reaching the last register address.

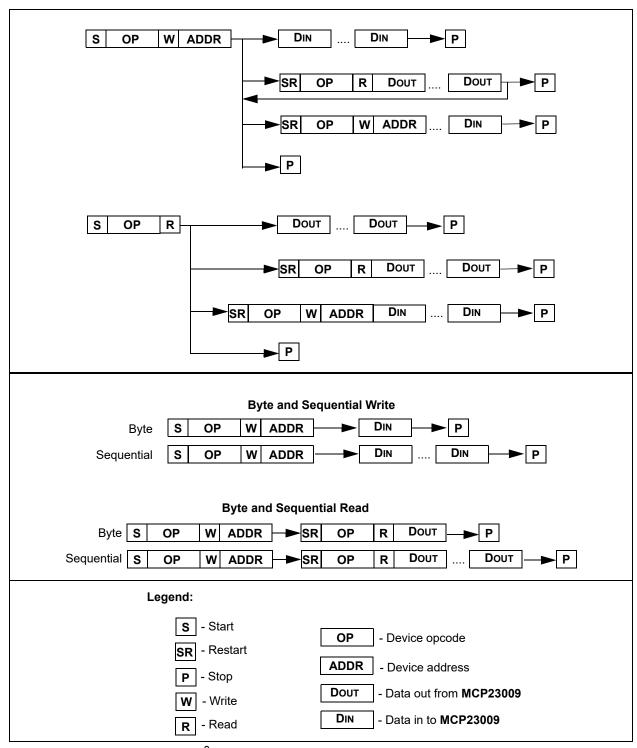


FIGURE 1-1: MCP23009 I^2C^{TM} Device Protocol.

1.4 Multi-Bit Address Decoder

The ADDR pin is used to set the client address of MCP23009 (I²C only) to allow up to eight devices on the bus using only a single pin. Typically, this would require three pins.

The multi-bit Address Decoder employs a basic FLASH ADC architecture (Figure 1-4). The seven comparators generate eight unique values based on the analog input. This value is converted to a 3-bit code which corresponds to the address bits (A2, A1, A0) in the serial OPCODE.

Sequence of operation (see Figure 1-5 for timings):

- Upon power-up (after VDD stabilizes), the module becomes active after time tADEN. Note that the analog value on the ADDR pin must be stable before this point to ensure accurate address assignment.
- 2. The 3-bit address is latched after tADDRLAT.
- The module powers down after the first rising edge of the serial clock is detected (tADDIS).

Once the address bits are latched, the device will keep the client address until a POR or Reset condition occurs.

1.4.1 CALCULATING VOLTAGE ON ADDR

When calculating the required voltage on the ADDR pin (V2), the set point should be the mid point of the LSb of the ADC.

The examples in Figures 1-2 and 1-3 show how to determine the mid-point voltage (V2) and the range of voltages based on a voltage divider circuit. The maximum tolerance is 20%, however, it is recommended to use 5% tolerance worst-case (10% total tolerance).

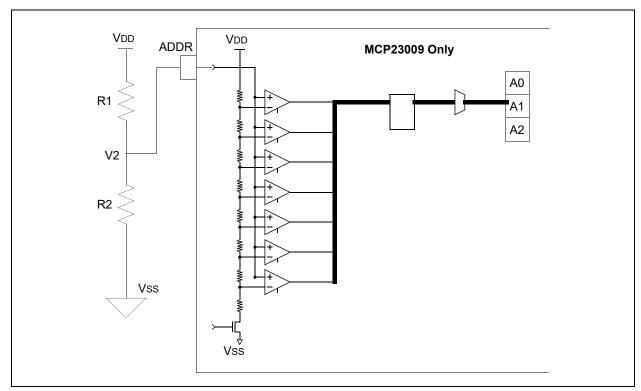


FIGURE 1-2: Voltage Divider Example.

Assume:

n = A2, A1, A0 in opcode ratio = R2/(R1+R2)

V2 = voltage on ADDR pin

 $V2(min) = V2 - (V_{DD}/8) \times \%$ tolerance

 $V2(max) = V2 + (V_{DD}/8) x \% tolerance$

			V _{DD} =	1.8	10% Tolera	ance (total)
n	R2 = 2n + 1	R1 = 16 - R2	R2/(R1 + R2)	V2	V2(min)	V2(max)
0	1	15	0.0625	0.113	0.00	0.14
1	3	13	0.1875	0.338	0.32	0.36
2	5	11	0.3125	0.563	0.54	0.59
3	7	9	0.4375	0.788	0.77	0.81
4	9	7	0.5625	1.013	0.99	1.04
5	11	5	0.6875	1.238	1.22	1.26
6	13	3	0.8125	1.463	1.44	1.49
7	15	1	0.9375	1.688	1.67	1.80

			$V_{DD} =$	2.7	10% Tolera	ance (total)
n	R2 = 2n + 1	R1 = 16 - R2	R2/(R1 + R2)	V2	V2(min)	V2(max)
0	1	15	0.0625	0.169	0.00	0.19
1	3	13	0.1875	0.506	0.48	0.53
2	5	11	0.3125	0.844	0.82	0.87
3	7	9	0.4375	1.181	1.16	1.20
4	9	7	0.5625	1.519	1.50	1.54
5	11	5	0.6875	1.856	1.83	1.88
6	13	3	0.8125	2.194	2.17	2.22
7	15	1	0.9375	2.531	2.51	2.70

			$V_{DD} =$	3.3	10% Tolera	ance (total)
n	R2 = 2n + 1	R1 = 16 - R2	R2/(R1 + R2)	V2	V2(min)	V2(max)
0	1	15	0.0625	0.206	0.00	0.23
1	3	13	0.1875	0.619	0.60	0.64
2	5	11	0.3125	1.031	1.01	1.05
3	7	9	0.4375	1.444	1.42	1.47
4	9	7	0.5625	1.856	1.83	1.88
5	11	5	0.6875	2.269	2.25	2.29
6	13	3	0.8125	2.681	2.66	2.70
7	15	1	0.9375	3.094	3.07	3.30

			$V_{DD} =$	5.5	10% Tolera	ance (total)
n	R2 = 2n + 1	R1 = 16 - R2	R2/(R1 + R2)	V2	V2(min)	V2(max)
0	1	15	0.0625	0.344	0.00	0.37
1	3	13	0.1875	1.031	1.01	1.05
2	5	11	0.3125	1.719	1.70	1.74
3	7	9	0.4375	2.406	2.38	2.43
4	9	7	0.5625	3.094	3.07	3.12
5	11	5	0.6875	3.781	3.76	3.80
6	13	3	0.8125	4.469	4.45	4.49
7	15	1	0.9375	5.156	5.13	5.50

FIGURE 1-3: Voltage and Code Example.

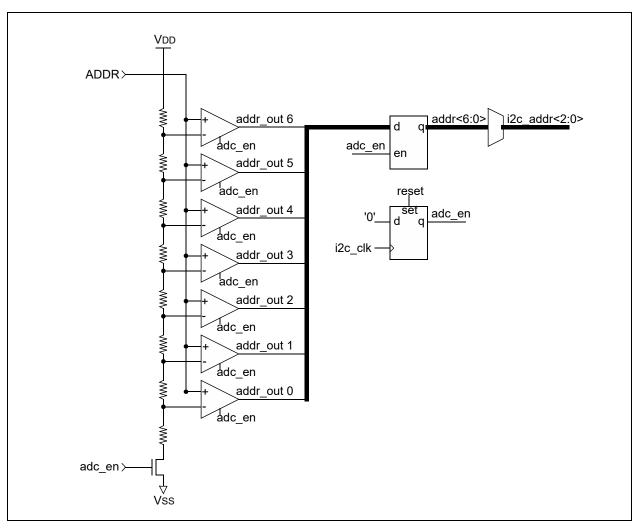


FIGURE 1-4: Flash ADC Block Diagram.

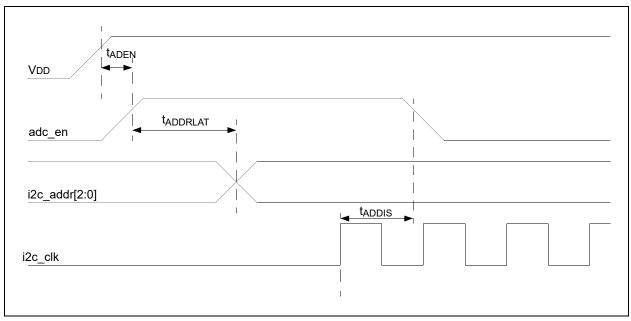


FIGURE 1-5: Hardware Address Decode Timing.

1.4.2 ADDRESSING I²C DEVICES (MCP23009)

MCP23009 is a client I²C device that supports 7-bit client addressing, with the read/write bit filling out the control byte. The client address contains four fixed bits and three user-defined hardware address bits (configured via the ADDR pin). Figure 1-6 shows the control byte format.

1.4.3 ADDRESSING SPI DEVICES (MCP23S09)

MCP23S09 is a client SPI device. The client address contains seven fixed bits (no address bits), with the read/write bit filling out the control byte. Figure 1-7 shows the control byte format.

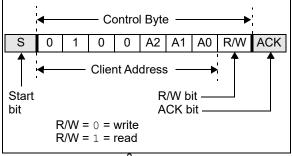


FIGURE 1-6: I^2C^{TM} Control Byte Format.

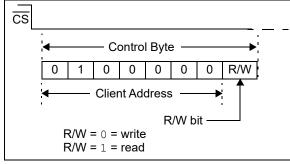


FIGURE 1-7: SPI Control Byte Format.

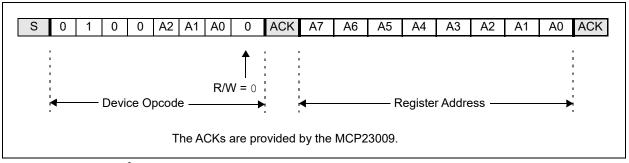


FIGURE 1-8: I^2C^{TM} Addressing Registers.

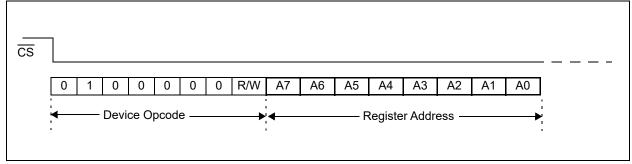


FIGURE 1-9: SPI Addressing Registers.

1.5 GPIO Port

The GPIO module is a general purpose 8-bit wide bidirectional port.

The outputs are open-drain.

The GPIO module contains the data ports (GPIOn), internal pull-up resistors and the output latches (OLATn).

The pull-up resistors are individually configured and can be enabled when the pin is configured as an input or output.

Reading the GPIOn register reads the value on the port. Reading the OLATn register only reads the latches, not the actual value on the port.

Writing to the GPIOn register actually causes a write to the latches (OLATn). Writing to the OLATn register forces the associated output drivers to drive to the level in OLATn. Pins configured as inputs turn off the associated output driver and put it in high impedance.

1.6 Configuration and Control Registers

There are eleven (11) registers associated with the MCP23X09, as shown in Table 1-4.

TABLE 1-4: CONFIGURATION AND CONTROL REGISTERS

Register Name	Address (hex)	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	POR/RST Value
IODIR	00	107	106	IO5	104	IO3	IO2	IO1	IO0	1111 1111
IPOL	01	IP7	IP6	IP5	IP4	IP3	IP2	IP1	IP0	0000 0000
GPINTEN	02	GPINT7	GPINT6	GPINT5	GPINT4	GPINT3	GPINT2	GPINT1	GPINT0	0000 0000
DEFVAL	03	DEF7	DEF6	DEF5	DEF4	DEF3	DEF2	DEF1	DEF0	0000 0000
INTCON	04	IOC7	IOC6	IOC5	IOC4	IOC3	IOC2	IOC1	IOC0	0000 0000
IOCON	05	_	_	SEQOP	_		ODR	INTPOL	INTCC	0000 0000
GPPU	06	PU7	PU6	PU5	PU4	PU3	PU2	PU1	PU0	0000 0000
INTF	07	INT7	INT6	INT5	INT4	INT3	INT2	INT1	INTO	0000 0000
INTCAP	08	ICP7	ICP6	ICP5	ICP4	ICP3	ICP2	ICP1	ICP0	0000 0000
GPIO	09	GP7	GP6	GP5	GP4	GP3	GP2	GP1	GP0	0000 0000
OLAT	0A	OL7	OL6	OL5	OL4	OL3	OL2	OL1	OL0	0000 0000

1.6.1 I/O DIRECTION REGISTER

This register controls the direction of the data I/O.

When a bit is set, the corresponding pin becomes an input. When a bit is clear, the corresponding pin becomes an output.

REGISTER 1-1: IODIR - I/O DIRECTION REGISTER

| R/W-1 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| 107 | IO6 | IO5 | 104 | IO3 | IO2 | IO1 | IO0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **IO<7:0>:** Controls the direction of data I/O <7:0>

1 = Pin is configured as an input0 = Pin is configured as an output

1.6.2 INPUT POLARITY REGISTER

This register allows the user to configure the polarity on the corresponding GPIO port bits.

If a bit is set, the corresponding GPIO register bit will reflect the inverted value on the pin.

REGISTER 1-2: IPOL – INPUT POLARITY PORT REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| IP7 | IP6 | IP5 | IP4 | IP3 | IP2 | IP1 | IP0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **IP<7:0>:** Controls the polarity inversion of the input pins <7:0>

1 = GPIO register bit will reflect the opposite logic state of the input pin

0 = GPIO register bit will reflect the same logic state of the input pin

1.6.3 INTERRUPT-ON-CHANGE CONTROL REGISTER

The GPINTEN register controls the Interrupt-on-Change feature for each pin.

If a bit is set, the corresponding pin is enabled for Interrupt-on-Change. The DEFVAL and INTCON registers must also be configured if any pins are enabled for Interrupt-on-Change.

REGISTER 1-3: GPINTEN - INTERRUPT-ON-CHANGE PINS

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| GPINT7 | GPINT6 | GPINT5 | GPINT4 | GPINT3 | GPINT2 | GPINT1 | GPINT0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 **GPINT<7:0>:** General-purpose I/O interrupt-on-change pins <7:0>

1 = Enable GPIO input pin for Interrupt-on-Change event

0 = Disable GPIO input pin for Interrupt-on-Change event

Refer to the INTCON and DEFVAL registers.

1.6.4 DEFAULT COMPARE REGISTER FOR INTERRUPT-ON-CHANGE

The default comparison value is configured in the DEFVAL register. If enabled (via GPINTEN and INTCON) to compare against the DEFVAL register, an opposite value on the associated pin will cause an Interrupt to occur.

REGISTER 1-4: DEFVAL - DEFAULT VALUE REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| DEF7 | DEF6 | DEF5 | DEF4 | DEF3 | DEF2 | DEF1 | DEF0 |
| bit 7 | | | | | | | bit 0 |

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 7-0 **DEF<7:0>:** Sets the compare value for pins configured for Interrupt-on-Change from defaults <7:0>. Refer to the INTCON register.

If the associated pin level is the opposite from the register bit, an Interrupt occurs.

Refer to the INTCON and GPINTEN registers.

1.6.5 INTERRUPT CONTROL REGISTER

The INTCON register controls how the associated pin value is compared for the Interrupt-on-Change feature. If a bit is set, the corresponding I/O pin is compared against the associated bit in the DEFVAL register. If a bit value is clear, the corresponding I/O pin is compared against the previous value.

REGISTER 1-5: INTCON - INTERRUPT-ON-CHANGE CONTROL REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| IOC7 | IOC6 | IOC5 | IOC4 | IOC3 | IOC2 | IOC1 | IOC0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **IOC<7:0>:** Controls how the associated pin value is compared for Interrupt-on-Change <7:0>.

- 1 = Pin value is compared against the associated bit in the DEFVAL register
- 0 = Pin value is compared against the previous pin value

Refer to the DEFVAL and GPINTEN registers.

1.6.6 CONFIGURATION REGISTER

The Sequential Operation (SEQOP) bit controls the incrementing function of the address pointer. If the address pointer is disabled, the address pointer does not automatically increment after each byte is clocked during a serial transfer. This feature is useful when it is desired to continuously poll (read) or modify (write) a register.

The Open-Drain (ODR) control bit enables/disables the INT pin for open-drain configuration.

The Interrupt Polarity (INTPOL) bit sets the polarity of the INT pin. This bit is functional only when the ODR bit is cleared, configuring the INT pin as active push-pull.

The Interrupt Clearing Control (INTCC) bit configures how Interrupts are cleared. When set (INTCC = 1), the Interrupt is cleared when the INTCAP register is read. When cleared (INTCC = 0), the Interrupt is cleared when the GPIO register is read.

The Interrupt can only be cleared when the Interrupt condition is inactive. Refer to **Section 1.7.4 "Clearing Interrupts"** for details.

REGISTER 1-6: IOCON - I/O EXPANDER CONFIGURATION REGISTER

U-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
_	_	SEQOP	_	_	ODR	INTPOL	INTCC
bit 7							bit 0

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 7	Unimplemented: Read as '0'
bit 6	Unimplemented: Read as '0'
bit 5	SEQOP: Sequential Operation mode bit.
	1 = Sequential operation disabled, address pointer does not increment0 = Sequential operation enabled, address pointer increments
bit 4	Unimplemented: Read as '0'
bit 3	Unimplemented: Read as '0'
bit 2	ODR: Configures the INT pin as an open-drain output.
	1 = Open-drain output (overrides the INTPOL bit)
	0 = Active driver output (INTPOL bit sets the polarity)
bit 1	INTPOL: Sets the polarity of the INT output pin.
	1 = Active-High
	0 = Active-Low
bit 0	INTCC: Interrupt Clearing Control 1 = Reading INTCAP register clears the Interrupt 0 = Reading GPIO register clears the Interrupt

1.6.7 PULL-UP RESISTOR CONFIGURATION REGISTER

The GPPU register controls the pull-up resistors for the port pins. If a bit is set, the corresponding port pin is internally pulled up with an internal resistor.

REGISTER 1-7: GPPU – GPIO PULL-UP RESISTOR REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PU7 | PU6 | PU5 | PU4 | PU3 | PU2 | PU1 | PU0 |
| bit 7 | | | | | | | bit 0 |

Legend:				
R = Readable bit	W = Writable bit	table bit U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 7-0 **PU<7:0>:** Controls the internal pull-up resistors on each pin (when configured as an input or output) <7:0>.

1 = Pull-Up enabled

0 = Pull-Up disabled

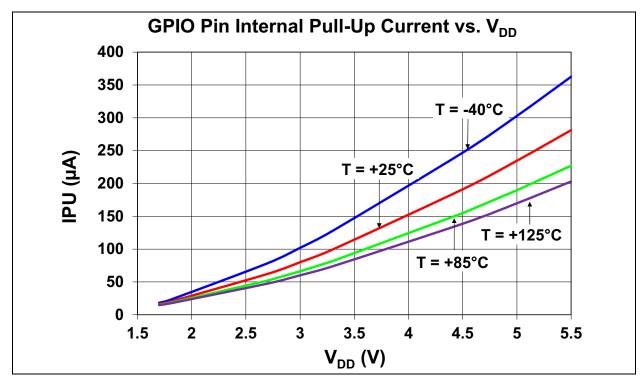


FIGURE 1-10: Typical Performance Curve for the Internal Pull-Up Resistors.

1.6.8 INTERRUPT FLAG REGISTER

The INTF register reflects the Interrupt condition on the port pins of any pin that is enabled for interrupts via the GPINTEN register. A set bit indicates that the associated pin caused the Interrupt.

This register is read-only. Writes to this register will be ignored.

REGISTER 1-8: INTF – INTERRUPT FLAG REGISTER

R-0	R-0	R-0	R-0	R-0	R-0	R-0	R-0
INT7	INT6	INT5	INT4	INT3	INT2	INT1	INT0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 7-0 **INT<7:0>:** Reflects the interrupt condition on the port. Will reflect the change only if interrupts are enabled (GPINTEN) <7:0>.

1 = Pin caused Interrupt

0 = Interrupt not pending

1.6.9 INTERRUPT CAPTURE REGISTER

The INTCAP register captures the GPIO port value at the time the Interrupt occurred. The register is read-only' and is updated only when an Interrupt occurs. The register will remain unchanged until the Interrupt is cleared via a read of INTCAP or GPIO.

REGISTER 1-9: INTCAP – INTERRUPT CAPTURED VALUE FOR PORT REGISTER

R-x	R-x	R-x	R-x	R-x	R-x	R-x R-x	
ICP7	ICP6	ICP5	ICP4	ICP3	ICP2	ICP1	ICP0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 ICP<7:0>: Reflects the logic level on the port pins at the time of Interrupt due to pin change <7:0>.

1 = Logic-High

0 = Logic-Low

1.6.10 PORT REGISTER

The GPIO register reflects the value on the port. Reading from this register reads the port. Writing to this register modifies the Output Latch (OLAT) register.

REGISTER 1-10: GPIO - GENERAL PURPOSE I/O PORT REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| GP7 | GP6 | GP5 | GP4 | GP3 | GP2 | GP1 | GP0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 **GP<7:0>:** Reflects the logic level on the pins <7:0>.

1 = Logic-High

0 = Logic-Low

1.6.11 OUTPUT LATCH REGISTER (OLAT)

The OLAT register provides access to the output latches. A read from this register results in a read of the OLAT and not the port itself. A write to this register modifies the output latches that modifies the pins configured as outputs.

REGISTER 1-11: OLAT – OUTPUT LATCH REGISTER 0

R/W-0 R/W-0							
OL7	OL6	OL5	OL4	OL3	OL2	OL1	OL0
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

-n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown

bit 7-0 **OL<7:0>:** Reflects the logic level on the output latch <7:0>.

1 = Logic-High

0 = Logic-Low

1.7 Interrupt Logic

If enabled, MCP23X09 activates the INT interrupt output when one of the port pins changes state or when a pin does not match the pre-configured default. Each pin is individually configurable as follows:

- · Enable/disable interrupt via GPINTEN
- Can Interrupt on either pin change or change from default as configured in DEFVAL

Both conditions are referred to as Interrupt-on-Change (IOC).

The Interrupt Control Module uses the following registers/bits:

- GPINTEN Interrupt enable register
- INTCON Controls the source for the IOC
- DEFVAL Contains the register default for IOC operation
- IOCON (ODR and INTPOL) Configures the INT pin as push-pull, open-drain and active level (high or low).

1.7.1 IOC FROM PIN CHANGE

If enabled, the MCP23X09 will generate an Interrupt if a mismatch condition exists between the current port value and the previous port value. Only IOC-enabled pins will be compared. See the GPINTEN and INTCON registers.

1.7.2 IOC FROM REGISTER DEFAULT

If enabled, the MCP23X09 will generate an Interrupt if a mismatch occurs between the DEFVAL register and the port. Only IOC-enabled pins will be compared. See the GPINTEN, INTCON and DEFVAL registers.

1.7.3 INTERRUPT OPERATION

The INT interrupt output can be configured as active-low, active-high or open-drain via the IOCON register.

Only those pins that are configured as an input (IODIR register) with Interrupt-on-Change (IOC) enabled (GPINTEN register) can cause an Interrupt. Pins configured as an output have no effect on the interrupt output pin.

Input change activity on a port input pin that is enabled for IOC will generate an internal device Interrupt and the device will capture the value of the port and copy it into INTCAP.

The first Interrupt event will cause the port contents to be copied into the INTCAP register. Subsequent Interrupt conditions on the port will not cause an Interrupt to occur as long as the Interrupt is not cleared by a read of INTCAP or GPIO.

1.7.4 CLEARING INTERRUPTS

The Interrupt will remain active until the INTCAP or GPIO register is read (depending on IOCON.INTCC). Writing to these registers will not affect the Interrupt. The Interrupt condition will be cleared after the LSb of the data is clocked out during a read operation of GPIO or INTCAP (depending on IOCON.INTCC).

Note:

Assuming IOCON.INTCC = 0 (INT cleared on GPIO read), the value in INTCAP can be lost if GPIO is read before INTCAP while another IOC is pending. After reading GPIO, the Interrupt will clear and then set due to the pending IOC, causing the INTCAP register to update.

1.7.5 INTERRUPT CONDITIONS

There are two possible configurations to cause Interrupts (configured via INTCON):

- Pins configured for Interrupt-on-Pin-Change will cause an Interrupt to occur if a pin changes to the opposite state. The default state is reset after an Interrupt occurs. For example, an Interrupt occurs by an input changing from 1 to 0. The new initial state for the pin is a logic 0.
- Pins configured for Interrupt-on-Change from register value will cause an Interrupt to occur if the corresponding input pin differs from the register bit. The Interrupt condition will remain as long as the condition exists, regardless of whether the INTAP or GPIO is read.

See Figures 1-11 and 1-12 for more information on the interrupt operations.

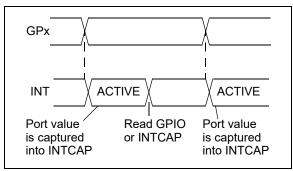


FIGURE 1-11: Interrupt-on-Pin-Change.

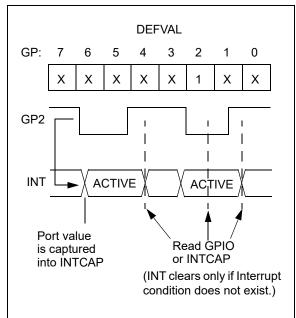


FIGURE 1-12: Interrupt-on-Change from Register Default.

2.0 ELECTRICAL CHARACTERISTICS

Absolute Maximum Ratings (†)

Ambient temperature under bias	
Storage temperature	–65°C to +150°C
Voltage on VDD with respect to Vss	0.3V to +7.0V
Voltage on RESET with respect to Vss	0.3V to +14V
Voltage on all other pins with respect to Vss (except VDD and GPIOA/B)	
Voltage on GPIO Pins	
Total power dissipation (Note 1)	700 mW
Maximum current out of Vss pin	200 mA
Maximum current into VDD pin	125 mA
Input clamp current, lik (Vi < 0 or Vi > VDD)	± 20 mA
Output clamp current, loκ (Vo < 0 or Vo > VDD)	± 20 mA
Maximum output current sunk by any output pin	25 mA
Maximum output current sunk by any output pin (VDD = 1.8V)	10 mA
ESD protection on all pins (HBM:MM)	4 kV:400V

[†] Notice: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Note 1: Power dissipation is calculated as follows: PDIS = VDD x {IDD $-\Sigma$ IOH} + Σ {(VDD - VOH) x IOH} + Σ (VOL x IOL).

2.1 DC Characteristics

ı	DC Characteristics		al Characteri: ≤ VDD ≤ 5.5\				icated, all limits are specified
Param. No.	Characteristic	Sym.	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
D001	Supply Voltage	VDD	1.8	_	5.5	V	
D002	VDD Start Voltage to Ensure Power-On Reset	VPOR	_	Vss	_	V	
D003	VDD Rise Rate to Ensure Power-On Reset	SVDD	0.05	_	_	V/ms	Design guidance only. Not tested.
D004	Supply Current	IDD	_	_	1	mA	SCL/SCK = 1 MHz
D005	Standby (Idle) current	IDDS	_	_	1	μA	-40°C ≤ TA ≤ +85°C
			_	_	6	μA	+85°C ≤ TA ≤ +125°C
	Input Low-Voltage						
D031	CS, GPIO, SCL/SCK, SDA, SI, RESET	VIL	Vss	_	0.2 VDD	V	
	Input High-Voltage						
D041	CS, SCL/SCK, SDA, SI, RESET	VIH	0.8 VDD	_	VDD	V	
	GPIO	VIH	0.8 VDD	_	5.5	V	
	Input Leakage Current						
D060	I/O port pins	lı∟	_	_	±1	μA	VSS ≤ VPIN ≤ VDD
	Output Leakage Current						
D065	I/O port pins	llo	_	_	±1	μA	VSS ≤ VPIN ≤ VDD
D070	GPIO internal pull-up current	lpu	_	220	_	μA	VDD = 5V, GP Pins = Vss (Note 1)
	Output Low-Voltage			•			
D080	GPIO	Vol	_	_	0.6	V	IOL = 8.5 mA, VDD = 4.5V (open-drain)
	INT		_	_	0.6		IOL = 1.6 mA, VDD = 4.5V
	SO, SDA		_	_	0.6		IOL = 3.0 mA, VDD = 1.8V
	SDA		_	_	0.8		IOL = 3.0 mA, VDD = 4.5V
	Output High-Voltage						
D090	INT, SO	Vон	VDD - 0.7		_	V	IOH = -3.0 mA, VDD = 4.5V
			VDD - 0.7				IOH = -400 μA, VDD = 1.8V
	Capacitive Loading Specs	on Outp	out Pins				
D101	GPIO, SO, INT	Cio			50	pF	These are load conditions
D102	SDA	Св	_	_	400 ⁽¹⁾		for the timing specifications. Refer to Figure 2-1. SDA test condition is 135 pF.

Note 1: This parameter is characterized, not 100% tested.

^{2:} Data in the Typical ("Typ") column is at 5V, +25°C, unless otherwise stated.

2.2 AC CHARACTERISTICS

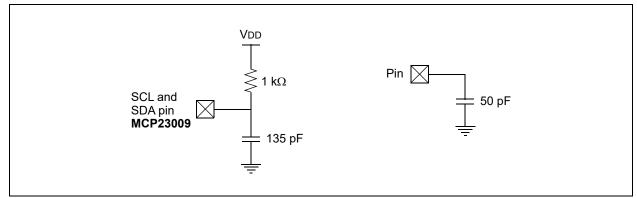


FIGURE 2-1: Load Conditions for Device Timing Specifications.

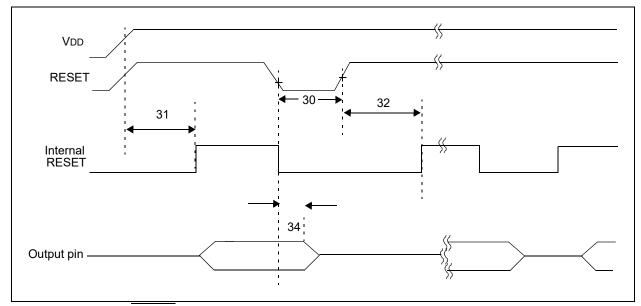


FIGURE 2-2: RESET and Device Reset Timer Timing.

TABLE 2-1: RESET AND DEVICE RESET TIMER REQUIREMENTS

AC Chara	cteristics	Electrical Characteristics: Unless otherwise indicated, all limits are specified for $1.8V \le VDD \le 5.5V$ at $-40^{\circ}C \le TA \le +125^{\circ}C$.							
Param. No.	Sym.	Characteristic	Min.	Typ. ⁽²⁾	Max.	Units	Conditions		
30	TRSTL	RESET Pulse Width (low)	1	_	_	μs	VDD = 5.0V		
32	THLD	Device active after reset high	_	0	_	μs	V _{DD} = 5.0V		
31	Tpor	POR at device power-up	_	20	_	μs	VDD = 5.0V		
34	Tıoz	Output high-impedance from RESET Low	_	_	1	μs			

Note 1: This parameter is characterized, not 100% tested.

2: Data in the Typical ("Typ") column is at 5V, +25°C, unless otherwise stated.

TABLE 2-2: GP AND INT PINS

AC Chara	cteristics	Electrical Characteristics: Unles $1.8V \le VDD \le 5.5V$ at $-40^{\circ}C \le TA$	rwise indicated, all limits are specified for 5°C.				
Param. No.	Sym.	Characteristic	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
50	tgpov	Serial data to output valid	_	_	500	ns	
51	tintd	Interrupt pin disable time	_	_	600	ns	
52	tgpiv	GP input change to register valid	_	450	_	ns	Note 1
53	tgpint	IOC event to INT active	_	_	600	ns	
54	tGLITCH	Glitch filter on GP pins	_		50	ns	Note 1

Note 1: This parameter is characterized, not 100% tested.

2: Data in the Typical ("Typ.") column is at 5V, +25°C, unless otherwise stated.

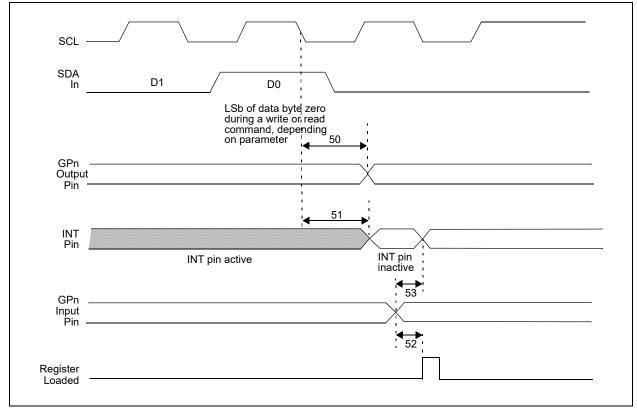


FIGURE 2-3: GPIO and INT Timing.

TABLE 2-3: HARDWARE ADDRESS LATCH TIMING

AC Chara	cteristics	Electrical Characteristics: Unless otherwise indicated, all limits are specified for $1.8V \le VDD \le 5.5V$ at $-40^{\circ}C \le TA \le +125^{\circ}C$.							
Param. No.	Sym.	Characteristic	Min.	Typ. ⁽²⁾	Max.	Units	Conditions		
40	taden	Time from VDD stable after POR to ADC enable		0		μs	Note 1		
41	taddrlat	Time from ADC enable to address decode and latch	_	50	_	ns	Note 1		
42	taddis	Time from raising edge of serial clock to ADC disable	_	10	_	ns	Note 1		

Note 1: This parameter is characterized, not 100% tested.

2: Data in the Typical ("Typ.") column is at 5V, +25°C, unless otherwise stated.

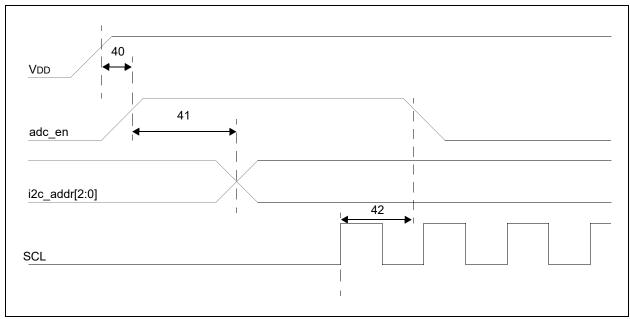


FIGURE 2-4: Hardware Address Latch Timing.

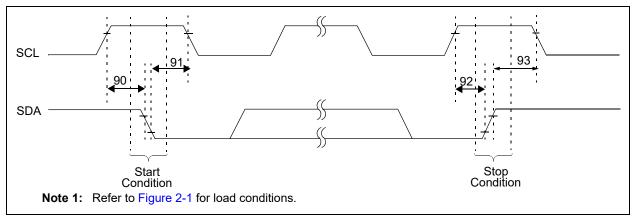


FIGURE 2-5: I^2C^{TM} Bus Start/Stop Bits Timing.

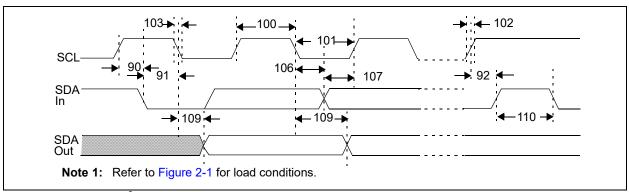


FIGURE 2-6: I^2C^{TM} Bus Data Timing.

TABLE 2-4: I²C™ BUS DATA REQUIREMENTS (CLIENT MODE)

l ²	C™ AC Characteristics	specified	al Characteristics: Unless otherwise indicated, all limits are d for 1.8V \leq VDD \leq 5.5V at -40°C \leq TA \leq +125°C, CL, SDA) = 1 k Ω , CL (SCL, SDA) = 135 pF.				
Param. No.	Characteristic	Sym.	Min.	Тур.	Max.	Units	Conditions
100	Clock High Time:	THIGH					
	100 kHz mode		4.0			μs	1.8V – 5.5V
	400 kHz mode		0.6			μs	1.8V – 5.5V
	3.4 MHz mode		0.06			μs	2.7V – 5.5V
101	Clock Low Time:	TLOW					
	100 kHz mode		4.7			μs	1.8V – 5.5V
	400 kHz mode		1.3	_	_	μs	1.8V – 5.5V
	3.4 MHz mode		0.16	_	_	μs	2.7V - 5.5V
102	SDA and SCL Rise Time:	Tr					
	100 kHz mode	(Note 1)	_		1000	ns	1.8V – 5.5V
	400 kHz mode		20 + 0.1 CB ⁽²⁾	_	300	ns	1.8V – 5.5V
	3.4 MHz mode		10		80	ns	2.7V – 5.5V
103	SDA and SCL Fall Time:	TF				•	
	100 kHz mode	(Note 1)	_	_	300	ns	1.8V – 5.5V
	400 kHz mode		20 + 0.1 CB ⁽²⁾		300	ns	1.8V – 5.5V
	3.4 MHz mode		10		80	ns	2.7V - 5.5V
90	Start Condition Setup Time:	Tsu:sta					l
	100 kHz mode		4.7		_	μs	1.8V – 5.5V
	400 kHz mode		0.6		_	μs	1.8V – 5.5V
	3.4 MHz mode		0.16	_	_	μs	2.7V - 5.5V
91	Start Condition Hold Time:	THD:STA					
	100 kHz mode		4.0		_	μs	1.8V – 5.5V
	400 kHz mode		0.6	_	_	μs	1.8V – 5.5V
	3.4 MHz mode		0.16	_	_	μs	2.7V - 5.5V
106	Data Input Hold Time:	THD:DAT				•	•
	100 kHz mode	1	0	_	3.45	μs	1.8V – 5.5V
	400 kHz mode		0	_	0.9	μs	1.8V – 5.5V
	3.4 MHz mode		0		0.07	μs	2.7V - 5.5V
107	Data Input Setup Time:	TSU:DAT			•	•	•
	100 kHz mode	1	250	_	_	ns	1.8V – 5.5V
	400 kHz mode	1	100	_	_	ns	1.8V – 5.5V
	3.4 MHz mode	1	0.01	_	_	μs	2.7V – 5.5V
92	Stop Condition Setup Time:	Tsu:sto			•	•	
	100 kHz mode	7	4.0		_	μs	1.8V – 5.5V
	400 kHz mode	1	0.6	_	_	μs	1.8V – 5.5V
	3.4 MHz mode	1	0.16	_	_	μs	2.7V – 5.5V

Note 1: This parameter is characterized, not 100% tested.

^{2:} CB is specified from 10 to 400 (pF).

^{3:} This parameter is not applicable in high-speed mode (3.4 MHz).

MCP23009/MCP23S09

TABLE 2-4: I²C™ BUS DATA REQUIREMENTS (CLIENT MODE) (CONTINUED)

l ²	C™ AC Characteristics	Electrical Characteristics: Unless otherwise indicated, all limits are specified for 1.8V \leq VDD \leq 5.5V at -40°C \leq TA \leq +125°C, RPU (SCL, SDA) = 1 k Ω , CL (SCL, SDA) = 135 pF.					+125°C,
Param. No.	Characteristic	Sym.	Min.	Тур.	Max.	Units	Conditions
109	Output Valid From Clock:	TAA					
	100 kHz mode			_	3.45	μs	1.8V – 5.5V
	400 kHz mode				0.9	μs	1.8V – 5.5V
	3.4 MHz mode			_	0.18	μs	2.7V – 5.5V
110	Bus Free Time:	TBUF					
	100 kHz mode	(Note 3)	4.7	_	_	μs	1.8V – 5.5V
	400 kHz mode		1.3	_		μs	1.8V – 5.5V
	3.4 MHz mode		N/A	_	N/A	μs	2.7V - 5.5V
	Bus Capacitive Loading:	Св					
	100 kHz and 400 kHz	(Note 2)	_	_	400	pF	Note 1
	3.4 MHz			_	100	pF	Note 1
	Input Filter Spike Suppression: (SDA and SCL)	Tsp					
	100 kHz and 400 kHz				50	ns	Note 1
	3.4 MHz		_	_	10	ns	Note 1

Note 1: This parameter is characterized, not 100% tested.

- 2: CB is specified from 10 to 400 (pF).
- 3: This parameter is not applicable in high-speed mode (3.4 MHz).

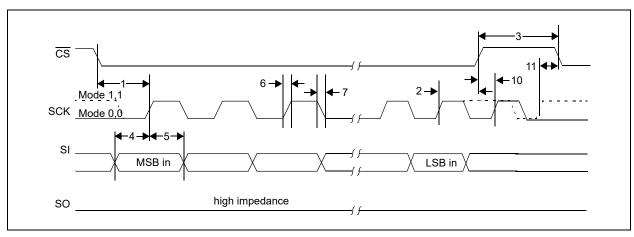


FIGURE 2-7: SPI Input Timing.

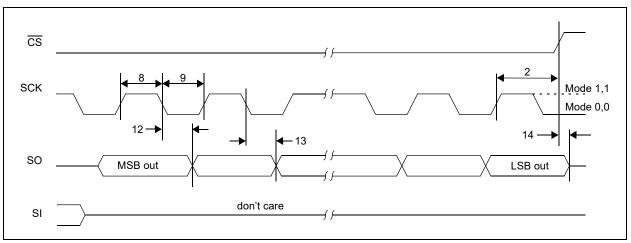


FIGURE 2-8: SPI Output Timing.

TABLE 2-5: SPI INTERFACE AC CHARACTERISTICS

SPI Inter	face AC Characteristics	Electrical Characteristics: Unless otherwise indicated, all limits are specified for $1.8V \le VDD \le 5.5V$ at $-40^{\circ}C \le TA \le +125^{\circ}C$.						
Param. No.	Characteristic	Sym.	Min.	Тур.	Max.	Units	Conditions	
	Clock Frequency	FCLK			10	MHz	1.8V – 5.5V	
1	CS Setup Time	Tcss	50		1	ns		
2	CS Hold Time	Тсѕн	50		1	ns	1.8V – 5.5V	
3	CS Disable Time	TCSD	50	_	_	ns	1.8V – 5.5V	
4	Data Setup Time	Tsu	10	_		ns	1.8V – 5.5V	
5	Data Hold Time	THD	10	_	_	ns	1.8V – 5.5V	
6	CLK Rise Time	Tr	_	_	2	μs	Note 1	
7	CLK Fall Time	TF	_	_	2	μs	Note 1	
8	Clock High Time	Тні	45	_	_	ns	1.8V – 5.5V	
9	Clock Low Time	TLO	45	1		ns	1.8V – 5.5V	
10	Clock Delay Time	TCLD	50	_	_	ns		
11	Clock Enable Time	TCLE	50	_	_	ns		
12	Output Valid from Clock Low	Tv	_	_	45	ns	1.8V – 5.5V	
13	Output Hold Time	Тно	0	_	_	ns		
14	Output Disable Time	TDIS		_	100	ns		

Note 1: This parameter is characterized, not 100% tested.

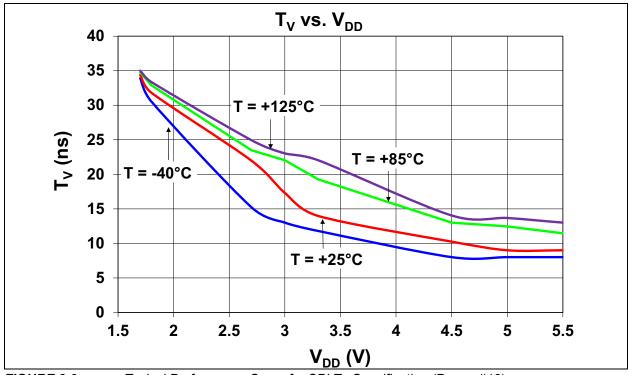
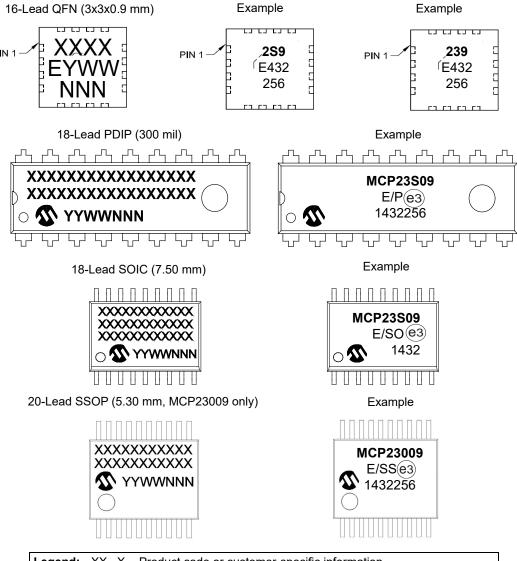


FIGURE 2-9: Typical Performance Curve for SPI T_V Specification (Param #12).

3.0 PACKAGING INFORMATION

3.1 Package Marking Information



Legend: XX...X Product code or customer-specific information

Y Year code (last digit of calendar year)
YY Year code (last 2 digits of calendar year)
WW Week code (week of January 1 is week '01')

NNN Alphanumeric traceability code

Pb-free JEDEC® designator for Matte Tin (Sn)

This package is Pb-free. The Pb-free JEDEC designator (e3) can be found on the outer packaging for this package.

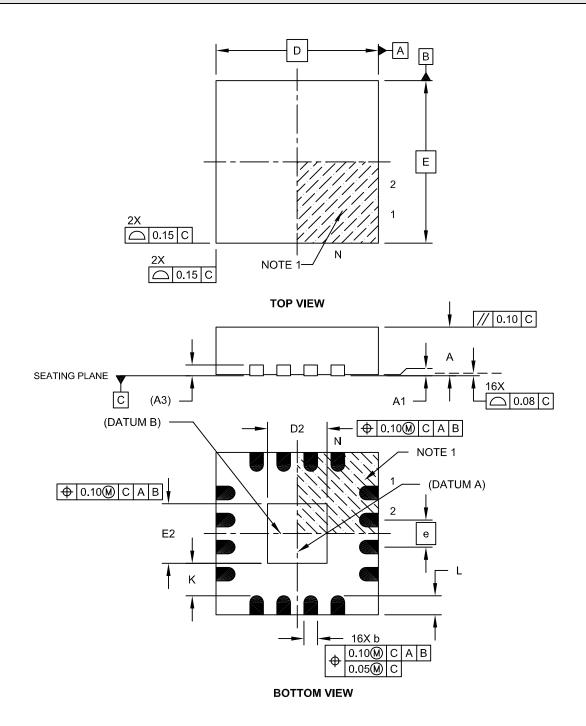
•, ▲, ▼ Pin one index is identified by a dot, delta up, or delta down (triangle mark).

Note: In the event the full Microchip part number cannot be marked on one line, it will be carried over to the next line, thus limiting the number of available characters for customer-specific information. Package may or may not include the corporate logo.

Underbar (_) and/or Overbar (¯) symbol may not be to scale.

16-Lead Plastic Quad Flat, No Lead Package (MG) - 3x3x0.9 mm Body [QFN]

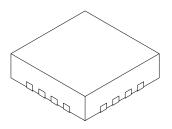
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-142A Sheet 1 of 2

16-Lead Plastic Quad Flat, No Lead Package (MG) - 3x3x0.9 mm Body [QFN]

te: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units			S	
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N		16		
Pitch	е		0.50 BSC		
Overall Height	Α	0.80 0.85 0.90			
Standoff	A1	0.00 0.02 0.05			
Contact Thickness	A3	0.20 REF			
Overall Width	Е	3.00 BSC			
Exposed Pad Width	E2	1.00	1.10	1.50	
Overall Length	D		3.00 BSC		
Exposed Pad Length	D2	1.00	1.10	1.50	
Contact Width	b	0.18 0.25 0.30			
Contact Length	L	0.25 0.35 0.45			
Contact-to-Exposed Pad	K	0.20	-	-	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated.
- 3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

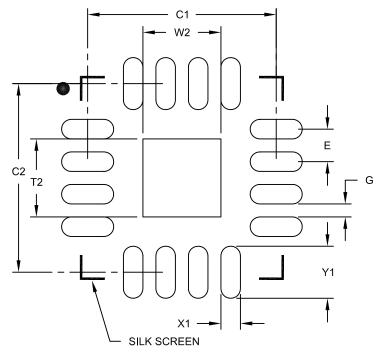
REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-142A Sheet 2 of 2

MCP23009/MCP23S09

16-Lead Plastic Quad Flat, No Lead Package (MG) – 3x3x0.9 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Contact Pitch	ntact Pitch E			
Optional Center Pad Width	W2			1.20
Optional Center Pad Length	T2	1.2		
Contact Pad Spacing	C1	2.90		
Contact Pad Spacing	C2		2.90	
Contact Pad Width (X16)	X1			0.30
Contact Pad Length (X16)	Y1			0.80
Distance Between Pads	G	0.20		

Notes:

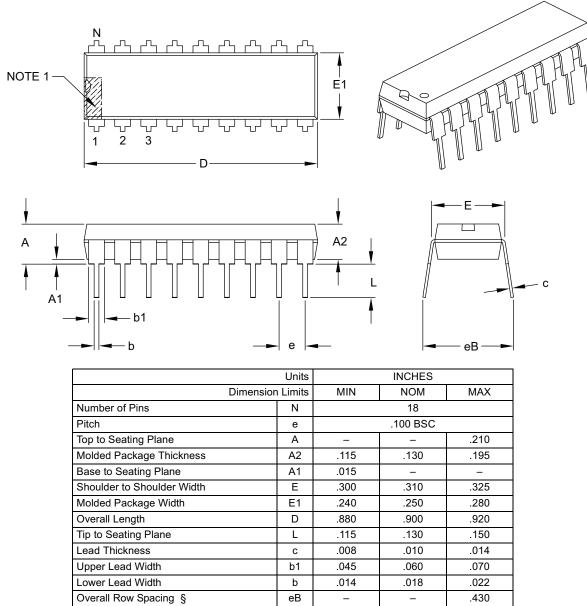
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2142A

18-Lead Plastic Dual In-Line (P) - 300 mil Body [PDIP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Notes:

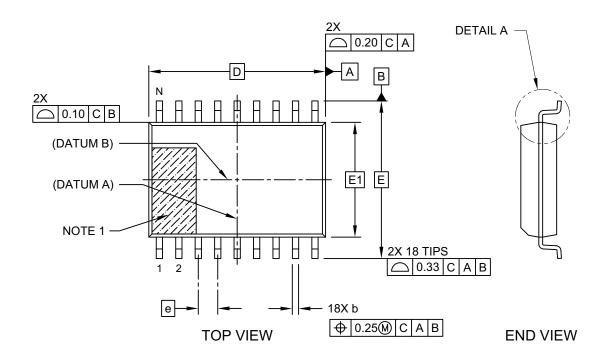
- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic.
- 3. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .010" per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M.

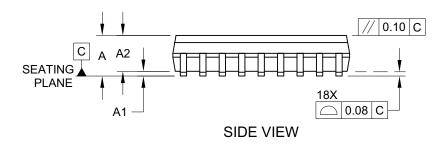
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-007B

18-Lead Plastic Small Outline (SO) - Wide, 7.50 mm (.300 In.) Body [SOIC]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

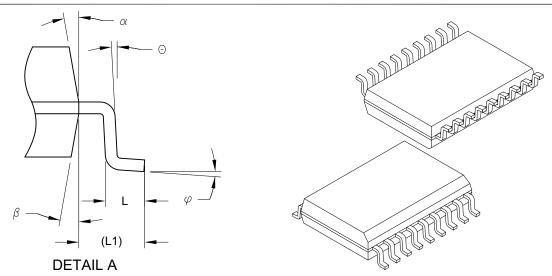




Microchip Technology Drawing C04-051D Sheet 1 of 2

18-Lead Plastic Small Outline (SO) - Wide, 7.50 mm (.300 ln.) Body [SOIC]

lote: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS				
Dimensior	Limits	MIN	MIN NOM		
Number of Pins	N		18		
Pitch	е		1.27 BSC		
Overall Height	Α	1	-	2.65	
Molded Package Thickness	A2	2.05	-	-	
Standoff §	A1	0.10 - 0.30			
Overall Width	Е	10.30 BSC			
Molded Package Width	E1	7.50 BSC			
Overall Length	D	11.55 BSC			
Chamfer (Optional)	h	0.25	-	0.75	
Foot Length	L	0.40	-	1.27	
Footprint	L1		1.40 REF		
Lead Angle	Θ	0°	-	1	
Foot Angle	φ	0°	-	8°	
Lead Thickness	С	0.20 - 0.33			
Lead Width	b	0.31 - 0.51			
Mold Draft Angle Top	α	5° - 15°			
Mold Draft Angle Bottom	β	5°	-	15°	

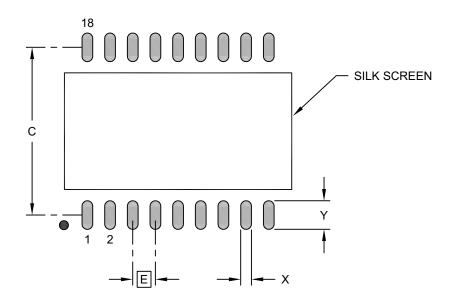
Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. § Significant Characteristic
- Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
- 4. Dimensioning and tolerancing per ASME Y14.5M
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.
 - REF: Reference Dimension, usually without tolerance, for information purposes only.
- 5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing No. C04-051D Sheet 2 of 2

18-Lead Plastic Small Outline (SO) - Wide, 7.50 mm (.300 ln.) Body [SOIC]

lote: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	Units	MILLIMETERS			
Dimens	ion Limits	MIN	MIN NOM		
Contact Pitch	E	1.27 BSC			
Contact Pad Spacing	С		9.40		
Contact Pad Spacing					
Contact Pad Width (X18)	Х			0.60	
Contact Pad Length (X18)	Y			1.90	

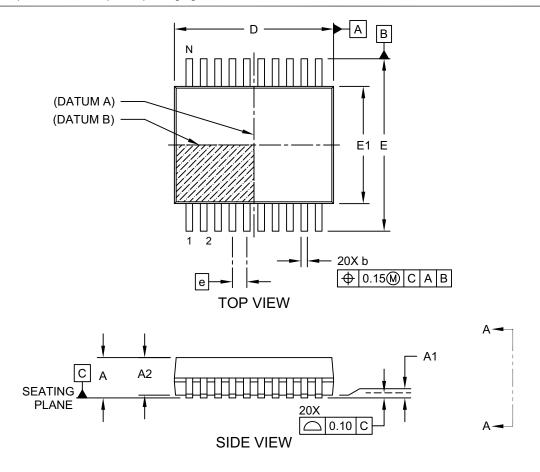
Notes:

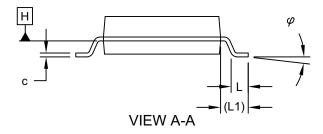
Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing C04-2051A

20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging

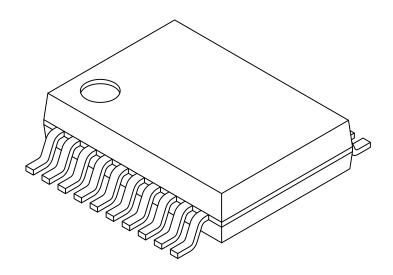




Microchip Technology Drawing C04-072 Rev C Sheet 1 of 2

20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MILLIMETERS			
Dimension	MIN	NOM	MAX	
Number of Pins	Ν		20	
Pitch	е		0.65 BSC	
Overall Height	Α	-	-	2.00
Molded Package Thickness	A2	1.65 1.75 1.85		
Standoff	A1	0.05		
Overall Width	Е	7.40	7.80	8.20
Molded Package Width	E1	5.00 5.30 5.6		
Overall Length	D	6.90 7.20 7.5		
Foot Length	L	0.55	0.75	0.95
Footprint	L1	1.25 REF		
Lead Thickness	С	0.09 - 0.25		
Foot Angle	φ	0°	4°	8°
Lead Width	b	0.22	-	0.38

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.20mm per side.
- 3. Dimensioning and tolerancing per ASME Y14.5M

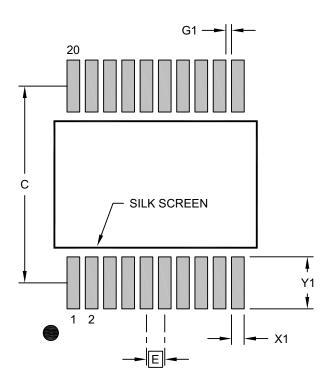
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-072 Rev C Sheet 2 of 2

20-Lead Plastic Shrink Small Outline (SS) - 5.30 mm Body [SSOP]

lote: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	Units				
	MILLIMETERS				
Dimension	Dimension Limits			MAX	
Contact Pitch	Е	0.65 BSC			
Contact Pad Spacing	С		7.00		
Contact Pad Width (X20)	X1			0.45	
Contact Pad Length (X20)	Y1			1.85	
Contact Pad to Center Pad (X18)	G1	0.20			

Notes:

- Dimensioning and tolerancing per ASME Y14.5M
 BSC: Basic Dimension. Theoretically exact value shown without tolerances.
- 2. For best soldering results, thermal vias, if used, should be filled or tented to avoid solder loss during reflow process

Microchip Technology Drawing C04-2072 Rev C

MCP23009/MCP23S09

APPENDIX A: REVISION HISTORY

Revision D (August 2022)

- Added information about the Automotive Qualification status of the device in Section "Features".
- Clarified Section 3.1 "Package Marking Information" to more closely match manufacturing standards.
- Updated Section "Product Identification System", with Automotive Qualified devices.
- · Minor text and format changes throughout.

Revision C (August 2014)

- Added ESD data in the Absolute Maximum Ratings (†) section.
- Updated Figure 1-1.
- Updated the DC Characteristics table.
- Updated the Package Marking Information section.
- · Minor typographical changes.

Revision B (May 2009)

- Added the 3x3 QFN package (MG package marking).
- · Updated Revision History.

Revision A (December 2008)

· Original Release of this Document.

PRODUCT IDENTIFICATION SYSTEM

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.

PART NO.	<u>-X</u>	/XX	XXX	Exa	imples:		
Device	 Temperature	Package	Qualification	a)	MCP23009-E	E/MG:	Extended Temperature, 16-Lead QFN package
	Range			b)	MCP23009-E	E/P:	Extended Temperature, 18-Lead PDIP package
Device:	MCP23009: MCP23009T:		der w/ I ² C™ Interface der w/ I ² C™ Interface	c)	MCP23009-E	E/SO:	Extended Temperature, 18-Lead SOIC package
	(Tape and Reel) MCP23S09: 8-Bit I/O Expander w/ SPI Interface MCP23S09T: 8-Bit I/O Expander w/ SPI Interface		d)	MCP23009T	E/SO:	Tape and Reel, Extended Temperature, 18-Lead SOIC package	
(Tape and Reel)		e)	MCP23009-E	E/SS:	Extended Temperature, 20-Lead SSOP package		
Temperature Range:	E = -40)°C to +125°C (E	Extended)	f)	MCP23009T	-E/SS:	Tape and Reel, Extended Temperature, 20-Lead SSOP package
Package:	3x3x	x0.9 mm Body, 1		g)	MCP23009-E	E/MGV/	AO: Extended Temperature, 16-Lead QFN package, Automotive Qualified
		P = Plastic Dual In-Line – 300 mil Body, 18-Lead		h)	MCP23009T	-E/MG\	/AO: Tape and Reel, Extended Temperature,
	Bod	y, 18-Lead	e – Wide, 7.50 mm				16-Lead QFN package, Automotive Qualified
		d Plastic Shrink) mm Body, 20-L	-	i)	MCP23S09-	E/MG:	Extended Temperature, 16-Lead QFN package
Qualification:	<blank> = Star</blank>			j)	MCP23S09T	-E/MG:	Tape and Reel, Extended Temperature,
	VAO = Auto	omotive AEC-Q1	00 Qualified	k)	MCP23S09-	E/P:	16-Lead QFN package Extended Temperature, 18-Lead PDIP package
				I)	MCP23S09-	E/SO:	Extended Temperature, 18-Lead SOIC package
				m)	MCP23S09T	-E/SO:	Tape and Reel, Extended Temperature, 18-Lead SOIC package
				N	catalo used the d Sales	og part n for orde evice pa GOffice	el identifier only appears in the umber description. This identifier is ring purposes and is not printed on ickage. Check with your Microchip for package availability with the el option.

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SYST-11ZUVO881 - Data Sheet - MCP23009/MCP23S09 - 8-Bit I/O Expander with Open-Drain Outputs Data

Affected Catalog Part Numbers(CPN)

MCP23009-E/SO

MCP23009-E/P

MCP23009-E/SS

MCP23009-E/MG

MCP23009-E/MGVAO

MCP23009T-E/SO

MCP23009T-E/SS

MCP23009T-E/MG

MCP23009T-E/MGVAO

MCP23S09-E/SO

MCP23S09-E/P

MCP23S09-E/MG

MCP23S09T-E/SO

MCP23S09T-E/MG